

Wide BVH traversal with a short stack

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Motivation

Ray tracing hardware acceleration easily constrained by memory bandwidth

- Compressed wide BVHs can reduce node bandwidth [Wald et al. 14, Ylitie et al. 17]
- Lossless meshlet compression can reduce geometry bandwidth
- Full stack can add additional bandwidth when stored to memory when procedural geometry is intersected
- → Need stack algorithm for wide BVHs with compact state



Previous Work

Stackless traversal with skip pointers [Smits 98]

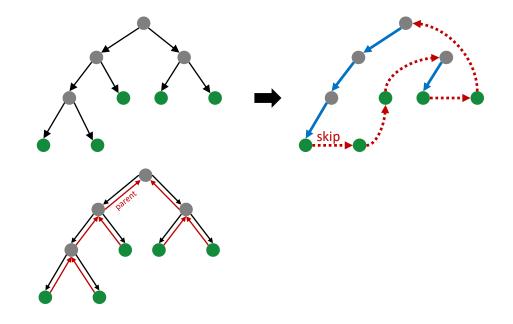
Enforces a fixed traversal order

Stackless traversal with backtracking to parent [Hapala et al. 11, Afra et al. 14]

- Allows front to back order
- Needs to re-intersect parent node

Binary BVH traversal with a restart trail [Laine 10]

- Maintain a restart trail and short stack of topmost entries
- Restart from root on an short stack underflow





BVH Traversal with a Restart Trail

A restart trail with short stack is well suited for fixed function ray tracing

- Short stack entries and the restart trail small
- Low overhead (10%) as short stack avoids most redundant traversal steps

Our Wide-BVHs restart trail algorithm builds on binary BVH traversal of [Laine 10]



Binary BVH Traversal with a Restart Trail

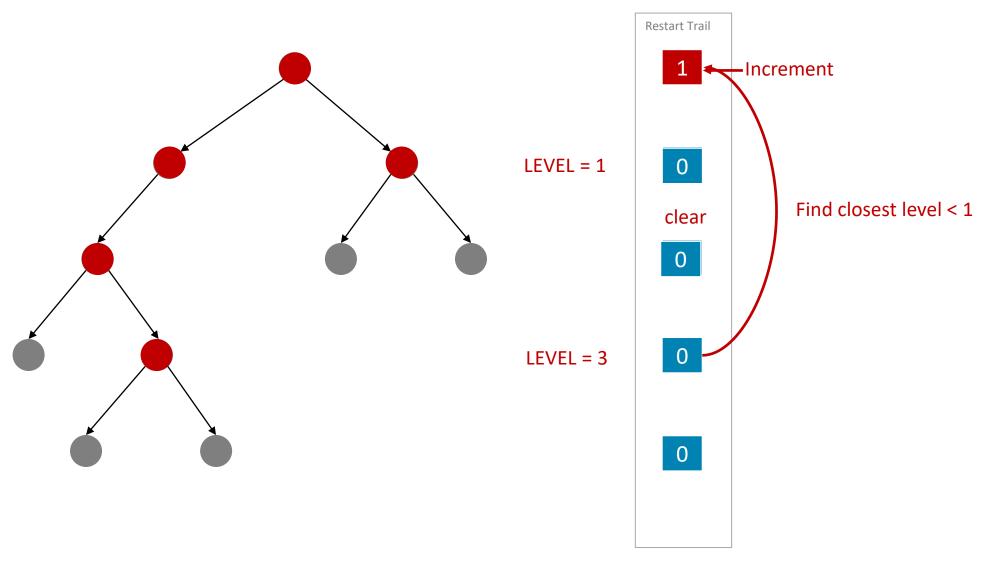
Assuming fixed front to back ordering of child nodes along the ray

Restart trail is bit vector (and depth) that encodes processed part of BVH

- RestartTrail[level] == 0 indicates that the **first child** is being traversed
- RestartTrail[level] == 1 indicates that the **last child** at the given *level* is being traversed
- → Pop operations can easily skip over finished levels



Binary Restart Trail





N-Wide BVH Traversal with a Restart Trail

Assuming fixed front to back ordering of child nodes along the ray

Restart trail is an integer vector (and depth) that encodes processed part of BVH

- RestartTrail[level] indicates the n'th child currently traversed
- RestartTrail[level] set to N-1 indicates the last child subtree being traversed
- → Pop operations can easily skip over finished levels



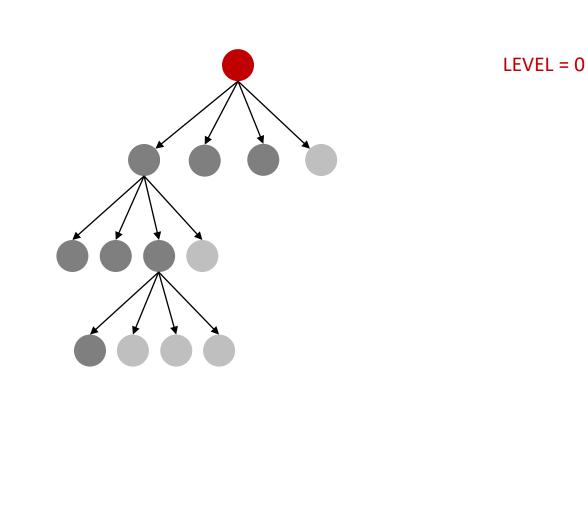
Detecting the Last Child

During down traversal the last child at a given level is detected when RestartTrail[level] == (number of intersections – 1)

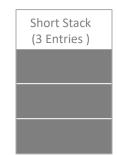
But we do not know if an entry popped from the short stack is the last child

- Therefore we use **one additional bit** per short stack entry to mark the last child when it is pushed onto the stack.
- Not required for binary BVH as popped nodes are always the last node.

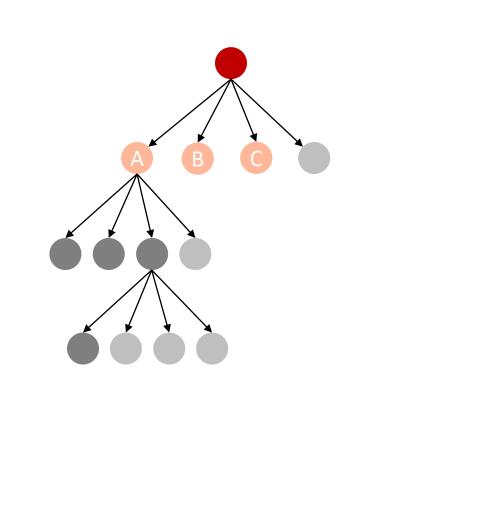


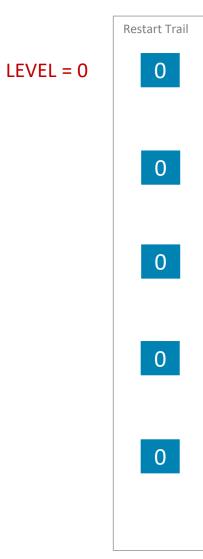


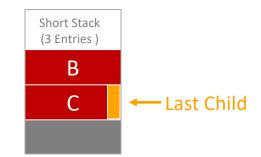
| Restart Trail |
|---------------|
| 0 |
| 0 |
| 0 |
| 0 |
| 0 |
| |



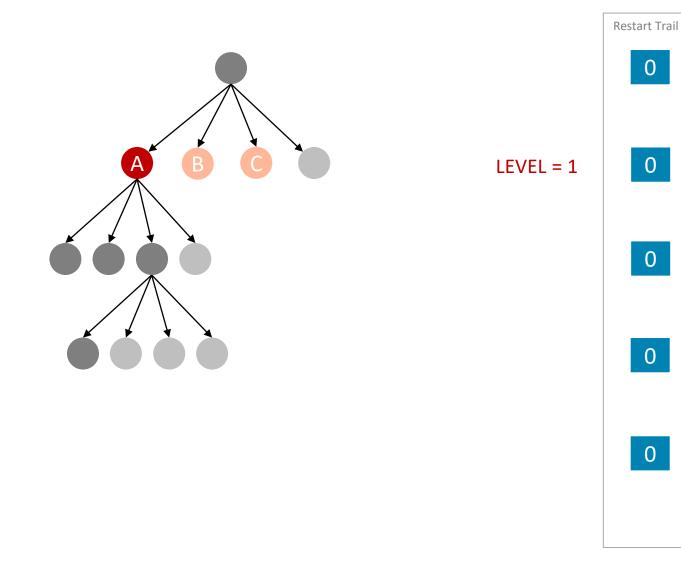


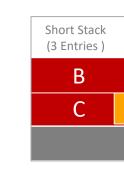




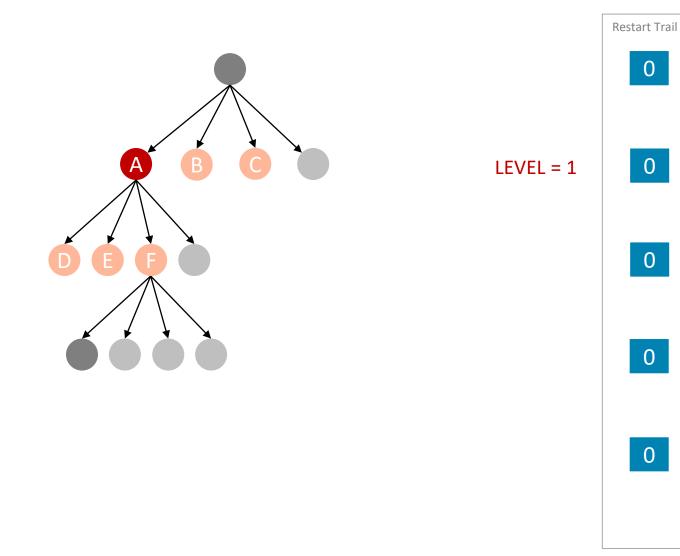


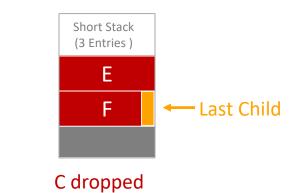






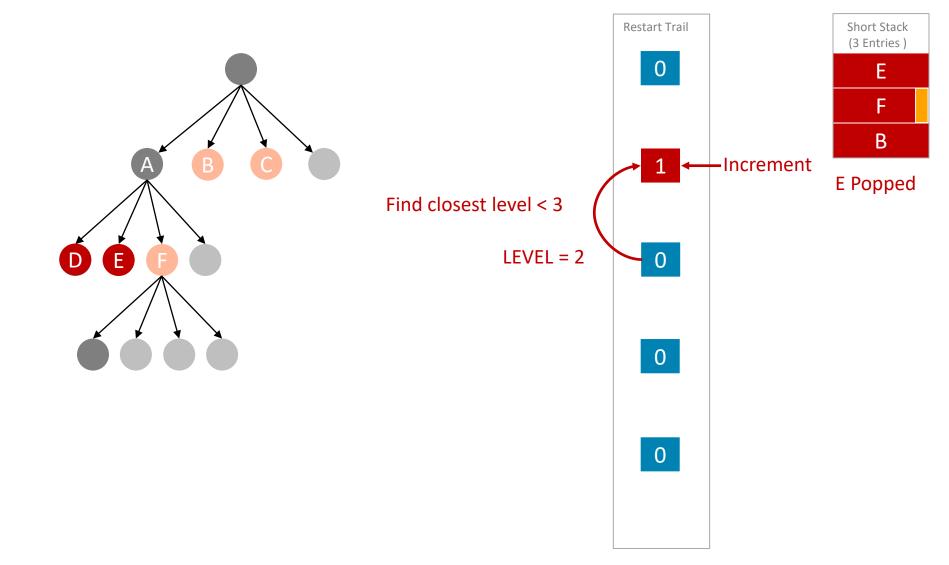




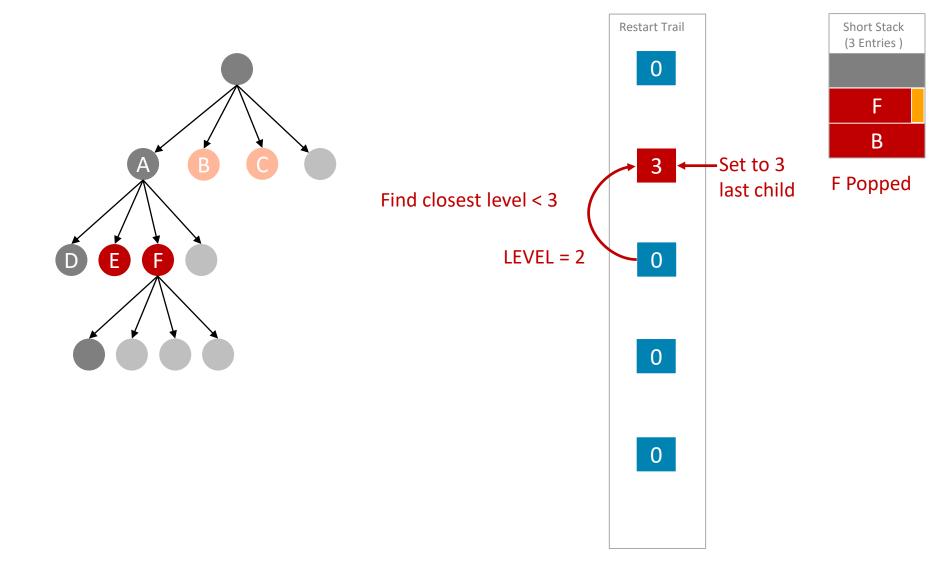


0

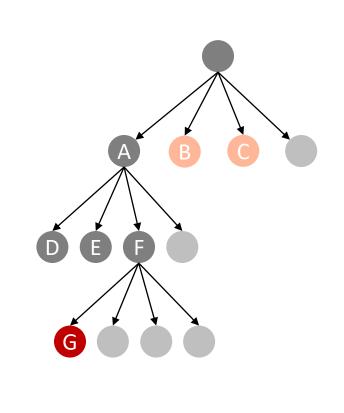


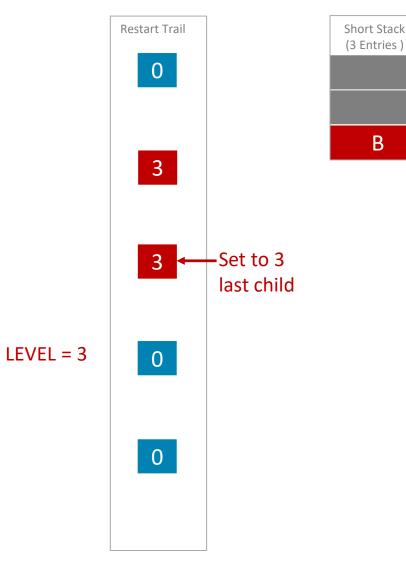






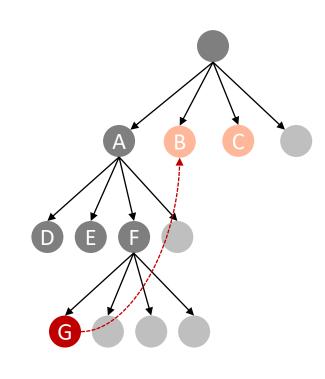


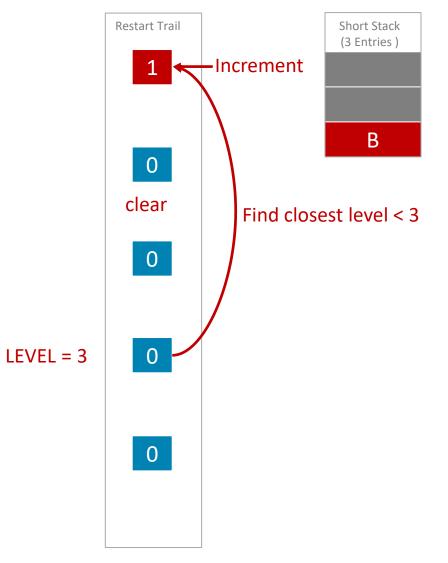




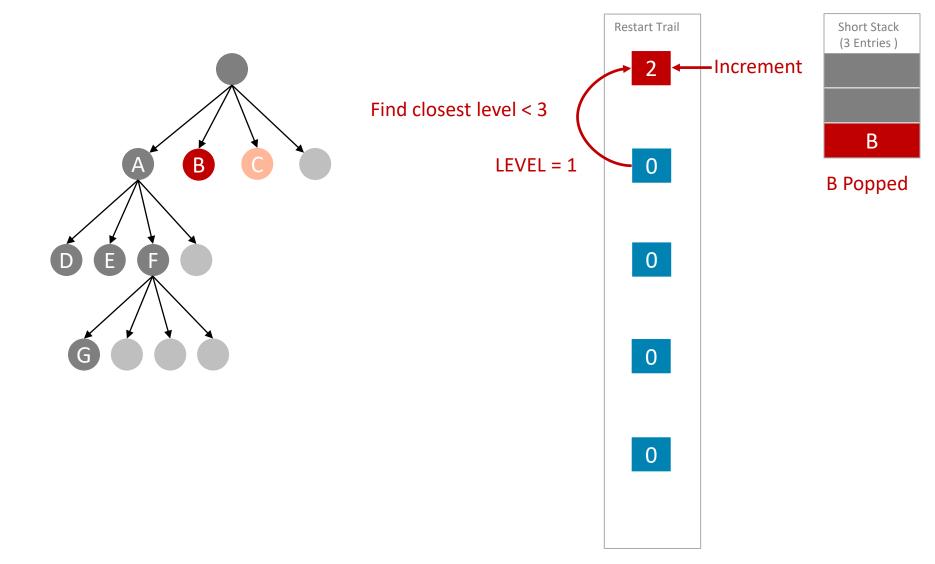
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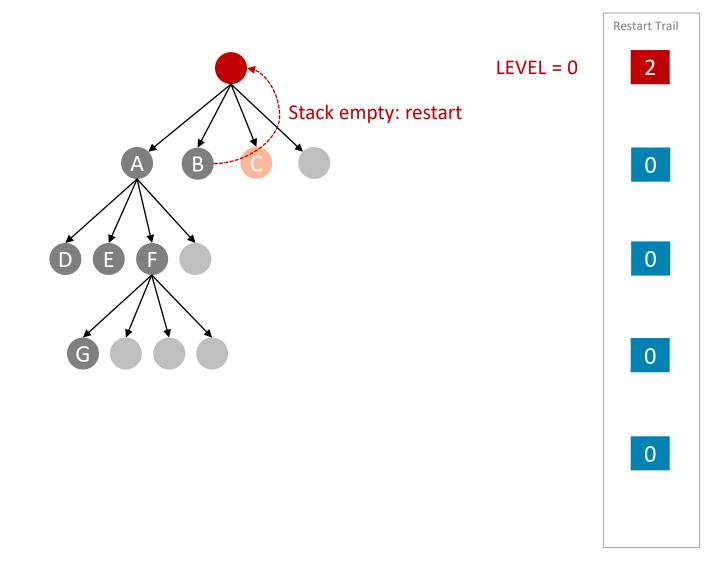


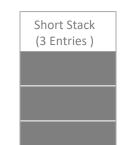




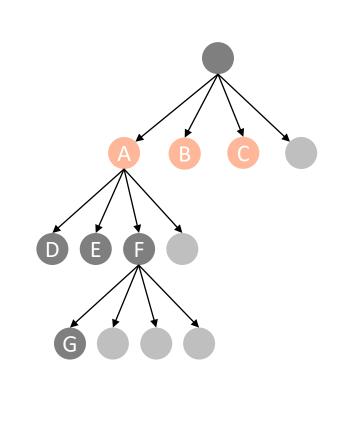








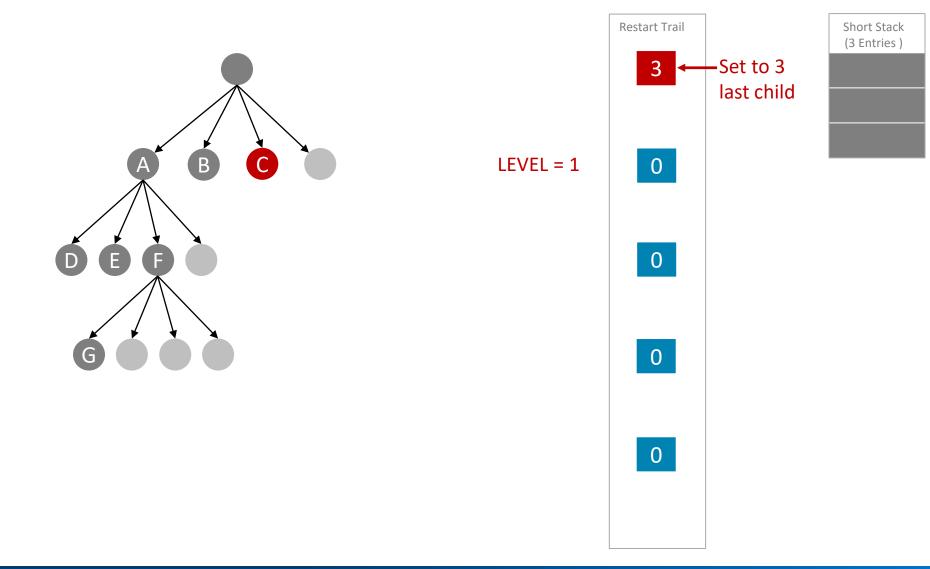




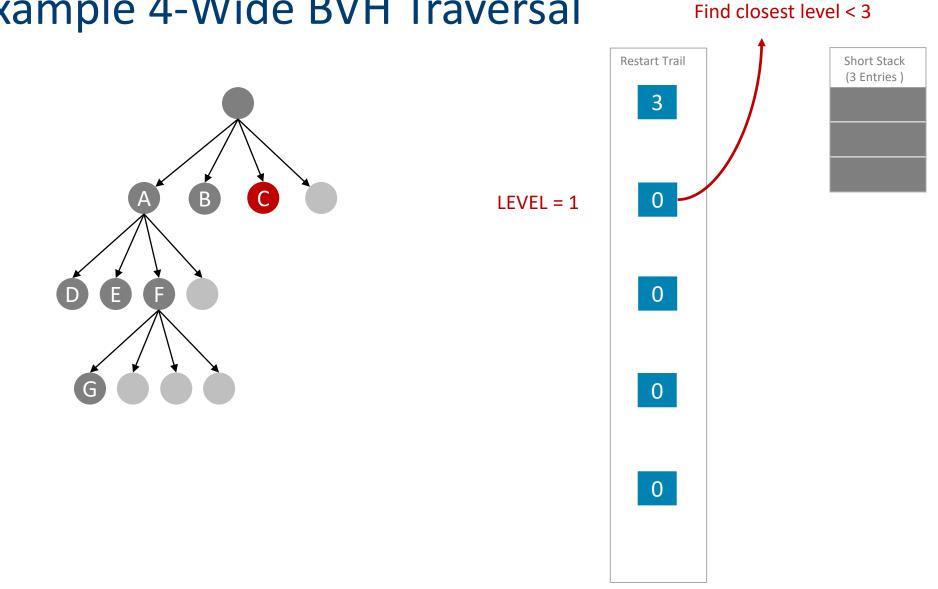
| LEVEL = 0 | Restart Trail |
|-----------|---------------|
| | 0 |
| | 0 |
| | 0 |
| | 0 |
| | |







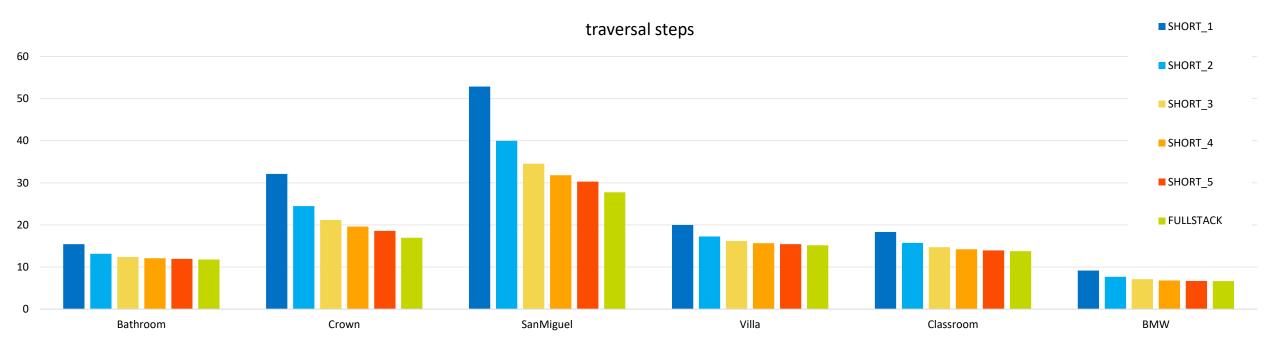






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Results for 6-wide BVH







Stack culling

- Storing near distance on the short stack would allow culling of popped nodes when a closer hit was found
- ➔ memory overhead
- Alternatively one can process closest child and push the parent node onto the short stack for later re-intersection
- → small culling overhead but often pays off



Conclusions

- Presented short stack with restart trail for wide BVHs
- Allows very compact stack storage at minimal overhead
- Suitable for fixed function ray tracing implementations



