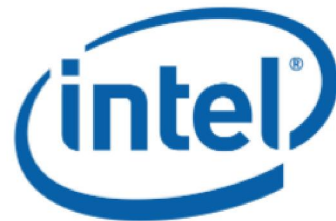


## Masked Software Occlusion Culling

Jon Hasselgren

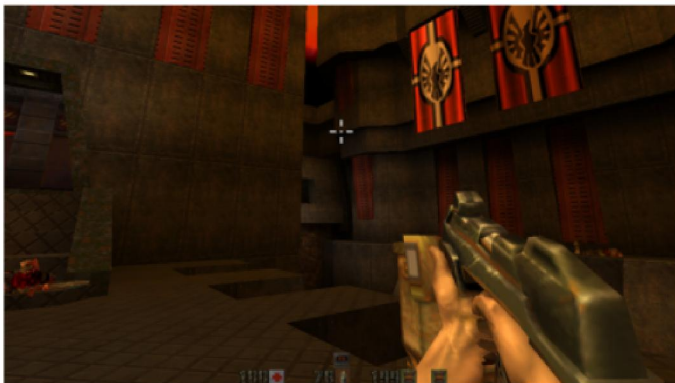
Magnus Andersson

Tomas Akenine-Möller



# Background

- **Potentially Visible Sets**
  - Precomputed – very efficient
  - Scene (occluders) must be static
  - Difficult to handle general scenes



Quake 2



Half-Life 2

# Background

- **Dynamic occlusion culling increasingly popular**
  - Modern games have more complex and dynamic worlds
  - Simpler content pipeline, no complex pre-computation



**Battlefield 4**



**Assassin's Creed Unity**

# Dynamic Occlusion Culling

---

- **Hardware occlusion queries**
  - GPU is extremely efficient at rasterization
  - Long pipeline delay, takes long to get the result of a query
  - May require sending result back to CPU
- **Software occlusion culling**
  - Short delay, no readback → easier to integrate with scene traversal
  - Software rasterization not as efficient as GPU

# Hierarchical Z Buffer (HiZ) [Greene93]

---

- Rasterize occluders to full resolution z buffer



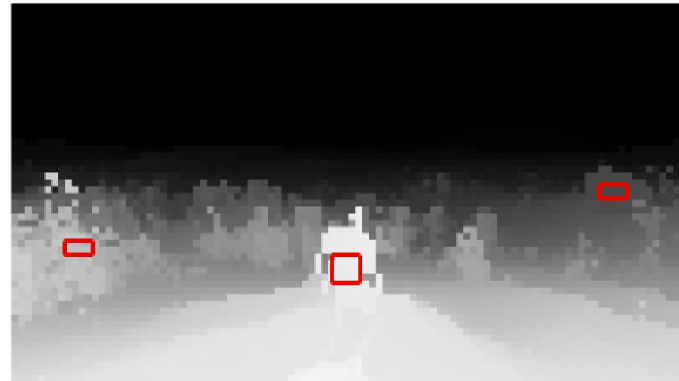
# Hierarchical Z Buffer (HiZ) [Greene93]

- Rasterize occluders to full resolution z buffer
- Create hierarchical z buffer
  - Find the maximum z in each 8x8 tile



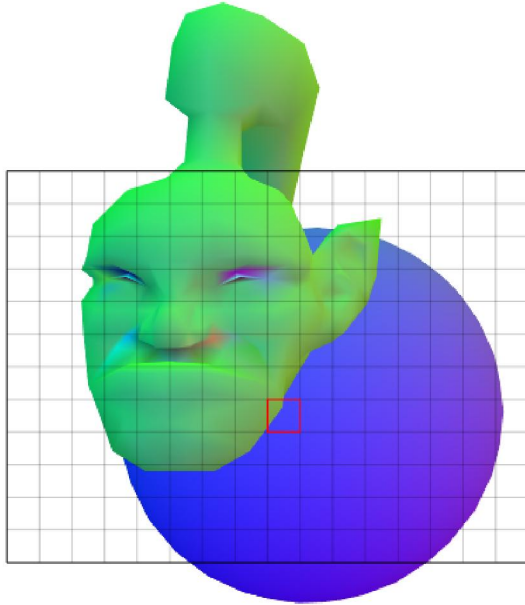
# Hierarchical Z Buffer (HiZ) [Greene93]

- Rasterize occluders to full resolution z buffer
- Create hierarchical z buffer
  - Find the maximum z in each 8x8 tile
- Perform occlusion queries with hierarchical z buffer



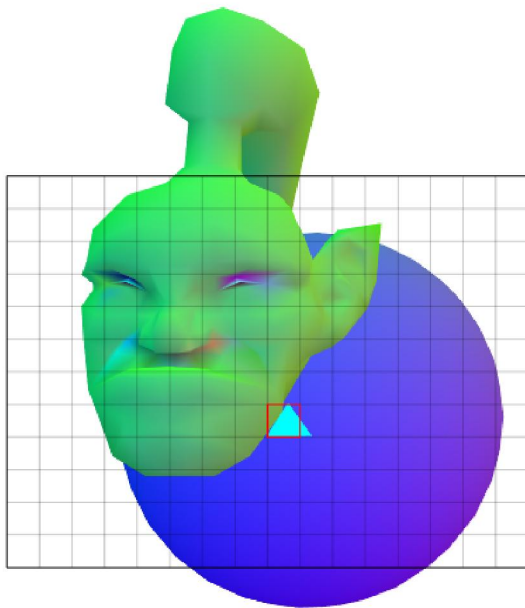
# Masked Depth Culling [AHAM15]

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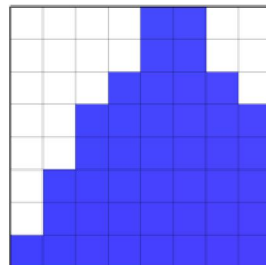


# Masked Depth Culling [AHAM15]

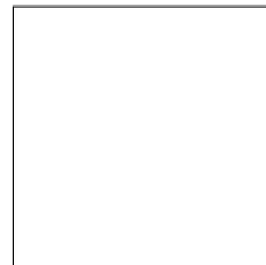


Hierarchical Z buffer  
[Greene93]

Depth buffer



HiZ buffer

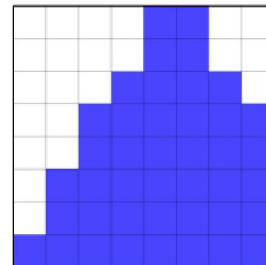


Masked depth buffer  
[AHAM15]

Depth buffer



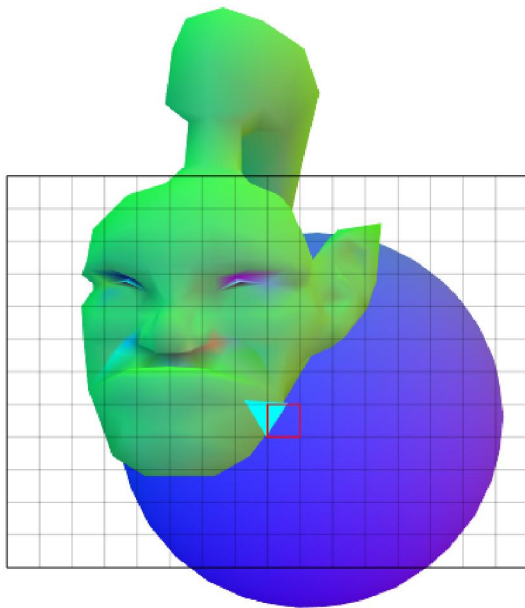
Masked HiZ buffer



$Z_{max}^0$

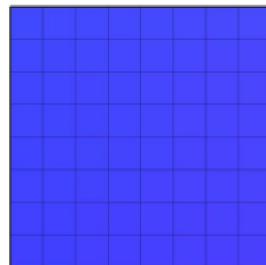
$Z_{max}^1$

# Masked Depth Culling [AHAM15]

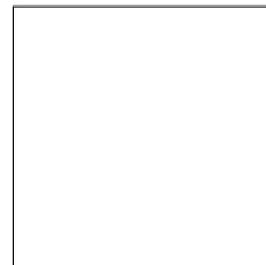


Hierarchical Z buffer  
[Greene93]

Depth buffer



HiZ buffer

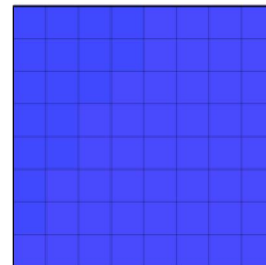


Masked depth buffer  
[AHAM15]

Depth buffer



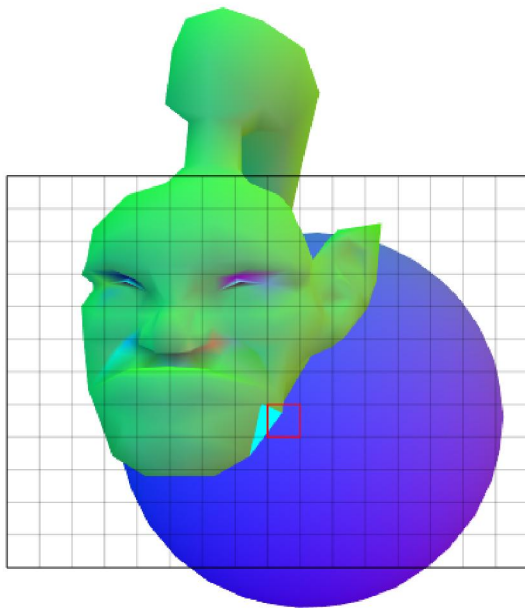
Masked HiZ buffer



$Z_{max}^0$

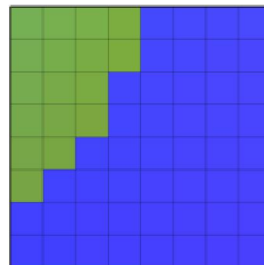
$Z_{max}^1$

# Masked Depth Culling [AHAM15]

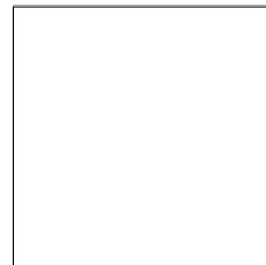


Hierarchical Z buffer  
[Greene93]

Depth buffer



HiZ buffer

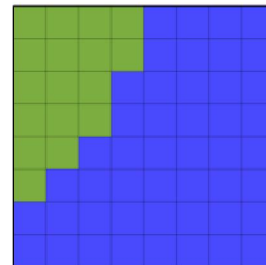


Masked depth buffer  
[AHAM15]

Depth buffer



Masked HiZ buffer



$Z_{max}^0$

$Z_{max}^1$

# Masked Software Occlusion Culling

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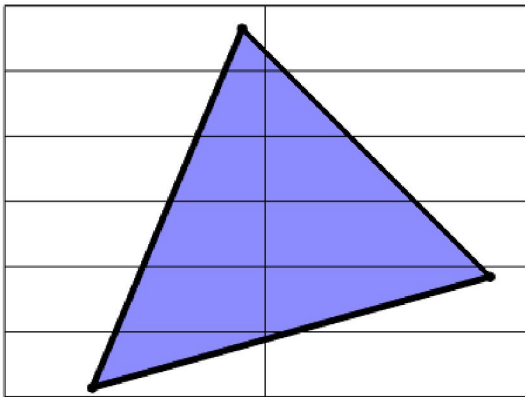
- **Masked Depth Culling [AHAM15]**
  - Was originally intended for graphics hardware
  - Directly update hierarchical z buffer without computing full res z buffer
  - Decouples coverage sampling (rasterization) and depth computation
- **Could it be really fast for software?**
  - Much less memory to read/write than full resolution z buffer
  - Updates use bitmasks, can process 256 pixels in parallel using AVX

---

# Algorithm

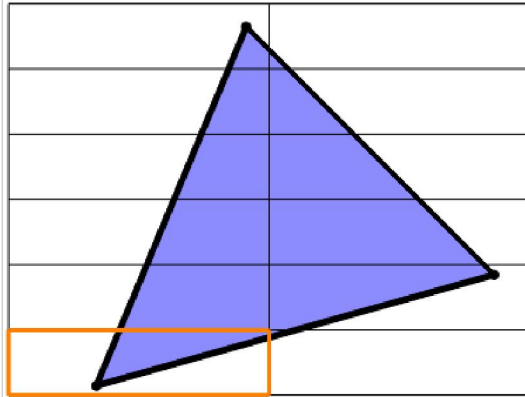
# Compute Bounding Box

- Padded to 32x8 pixel supertiles

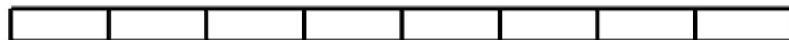
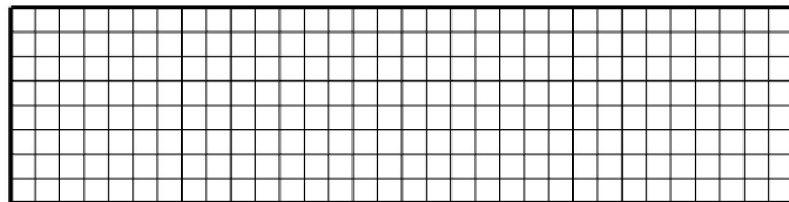
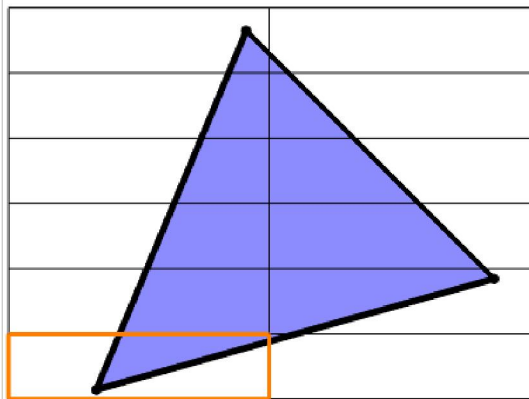


# Traverse Supertiles

---



# Traverse Supertiles

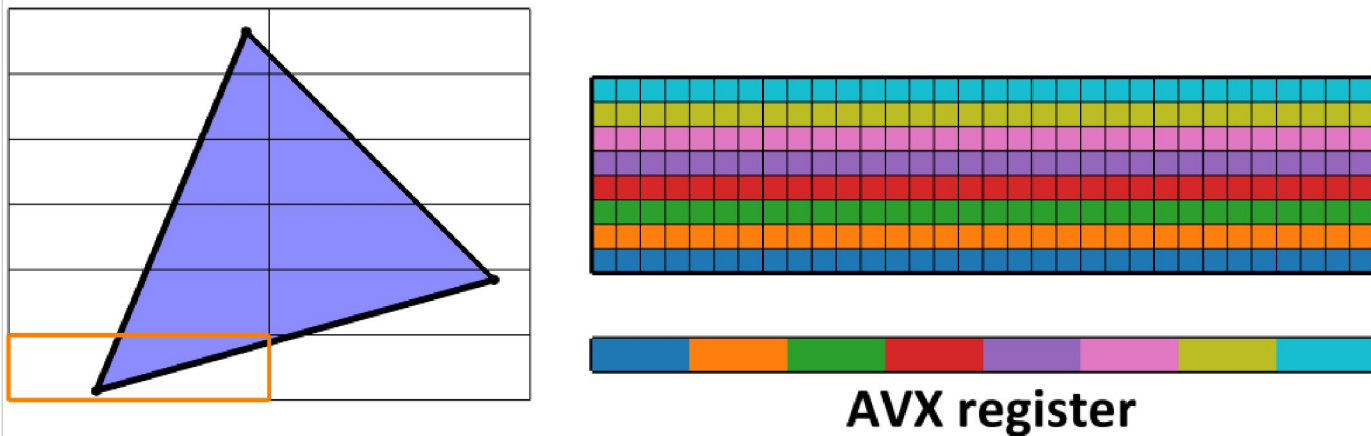


AVX register



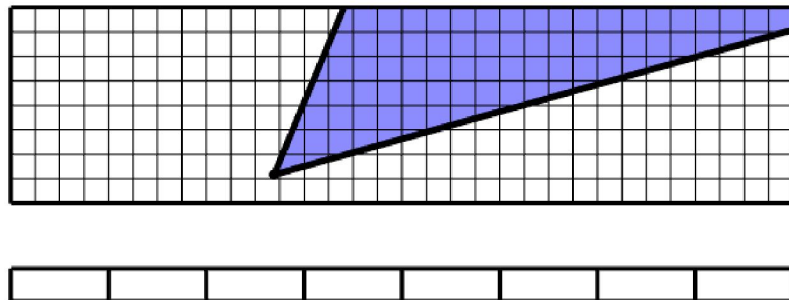
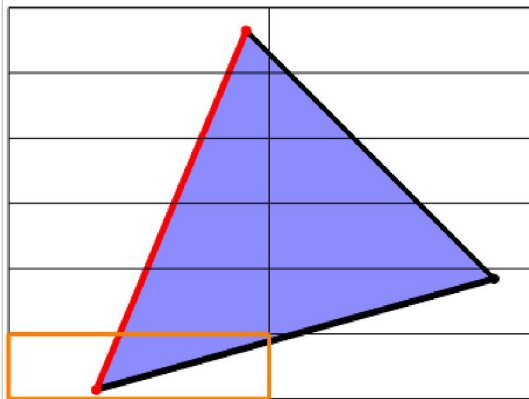
# AVX Register Layout

- One Scanline per SIMD-lane



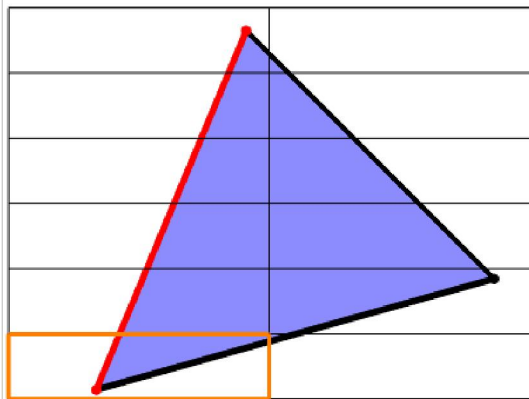
# Edge Slopes

- **Compute slopes ( $\Delta y/\Delta x$ ) during triangle setup**
  - Similar to regular scanline rasterizers
  - Some precision caveats due to tile size



# Compute Break Points

- **Compute break point for each scanline**
  - Eight scanlines in parallel using AVX

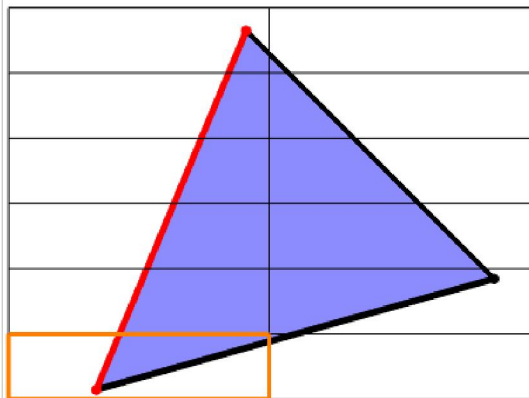


10	10	11	11	11	12	12	13
----	----	----	----	----	----	----	----

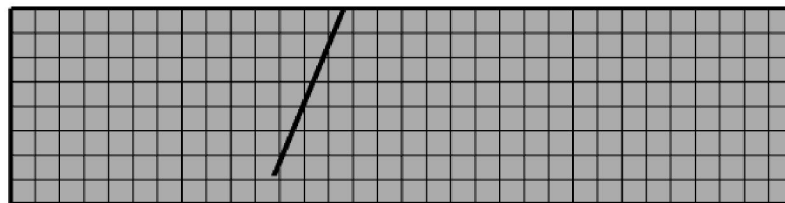
**Breakpoints**

# Compute Coverage Mask

- Start with full coverage mask



Coverage mask

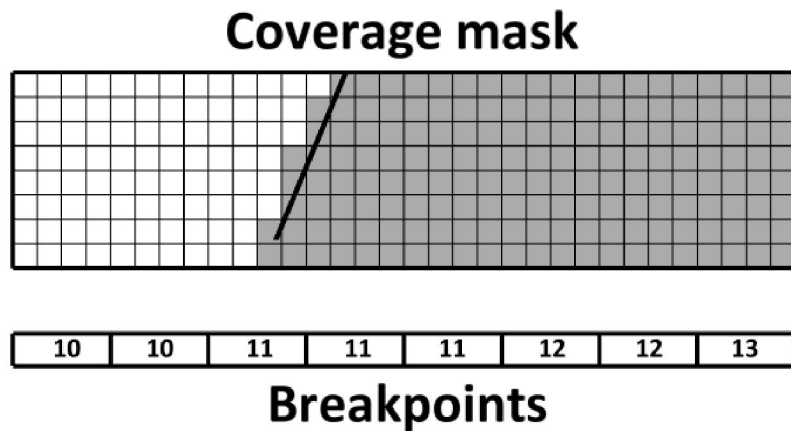
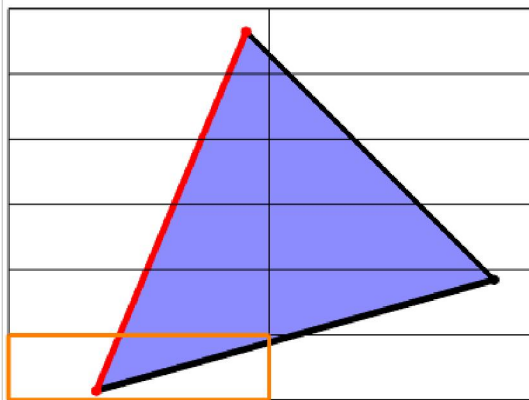


10	10	11	11	11	12	12	13
----	----	----	----	----	----	----	----

Breakpoints

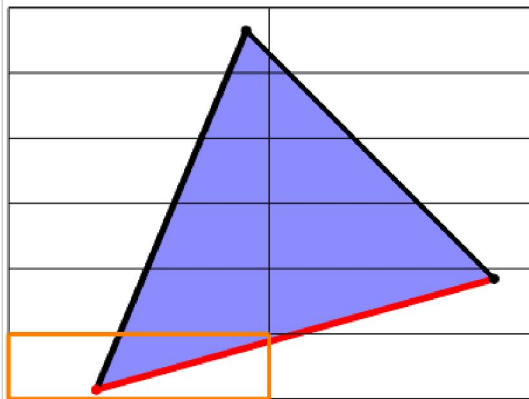
# Compute Coverage Mask

- **Start with full coverage mask**
  - Shift each lane (scan line) to break point
  - AVX2 and later support per-lane shift

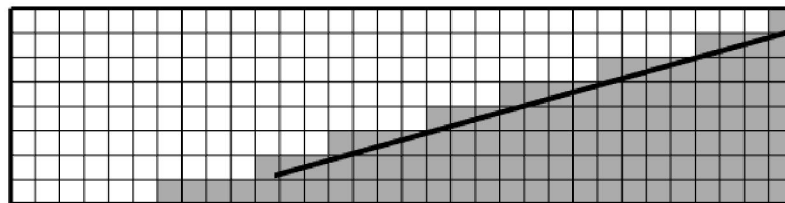


# Repeat for Next Edge

- Repeat the same process for next edge



Coverage mask

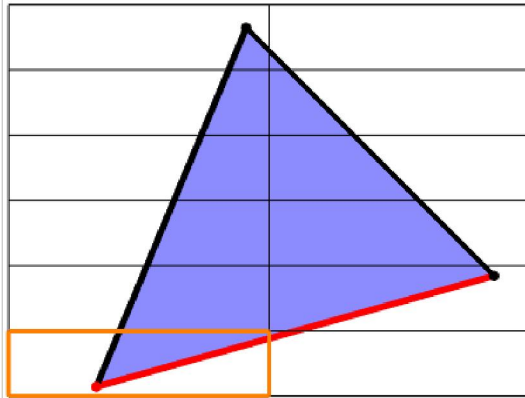


6	10	13	17	20	24	28	31
---	----	----	----	----	----	----	----

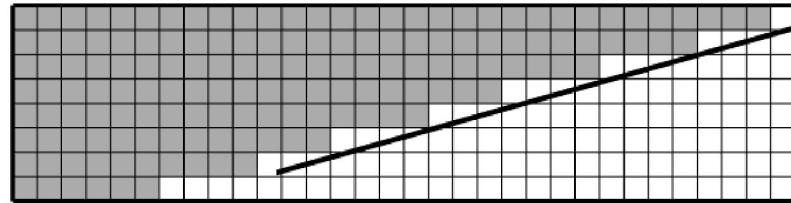
Breakpoints

# Repeat for Next Edge

- Repeat the same process for next edge
  - Edge is facing right → invert mask



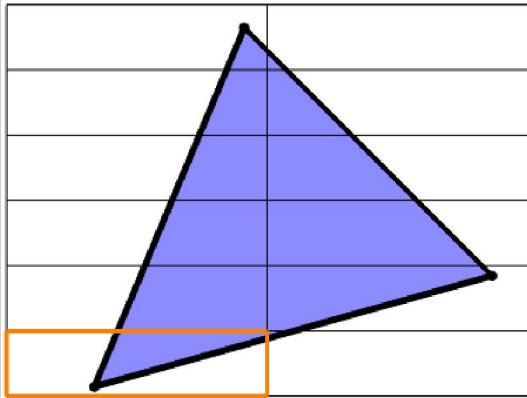
Coverage mask



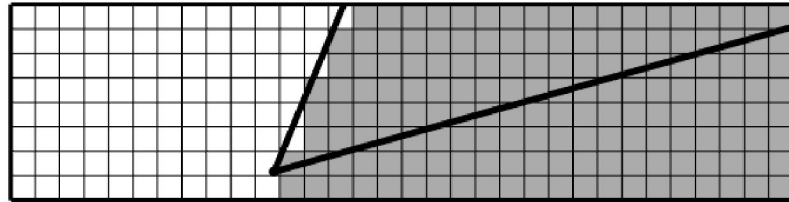
Breakpoints

# Combine Masks

- Combine mask of all overlapping edges



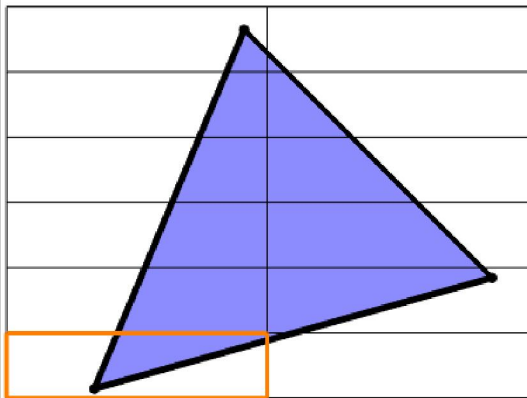
Coverage mask



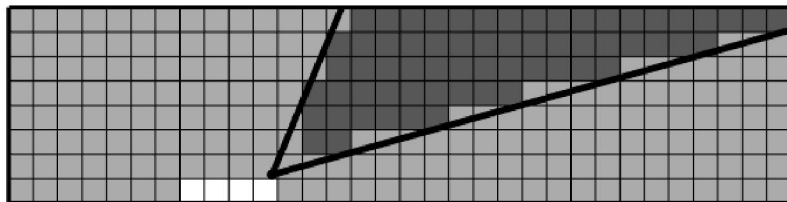


# Combine Masks

- **Combine mask of all overlapping edges**
  - Using bitwise AND

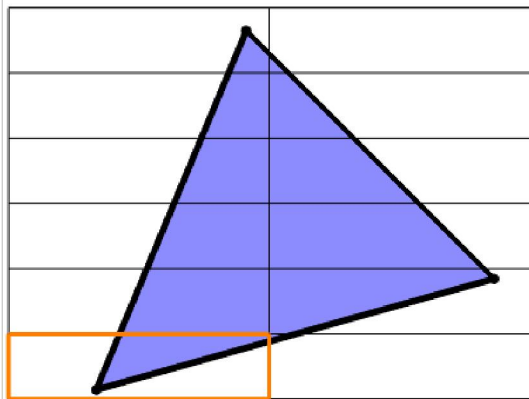


Coverage mask

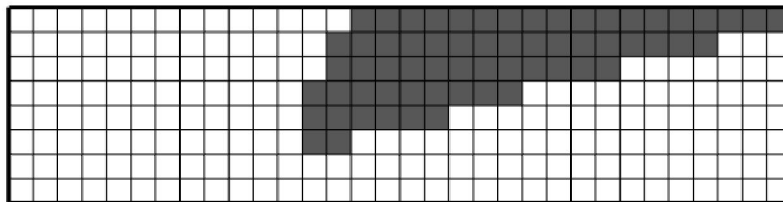


# Resulting Coverage Mask

- **Combine mask of all overlapping edges**
  - Using bitwise AND

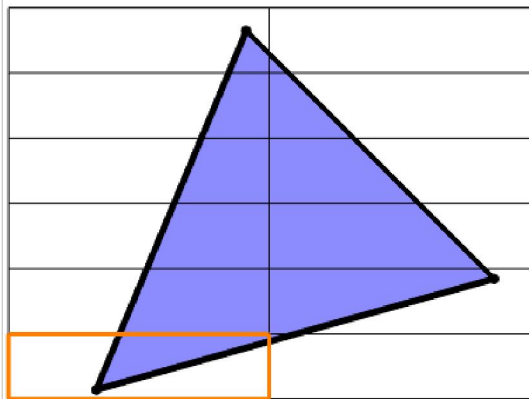


**Coverage mask**

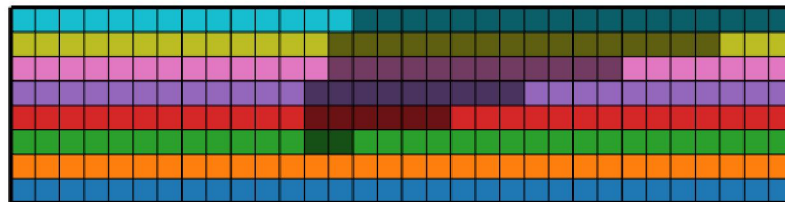


# Shuffle mask

- **Shuffle mask to form better shaped tiles**
  - Before: each SIMD-lane is a scanline



Coverage mask

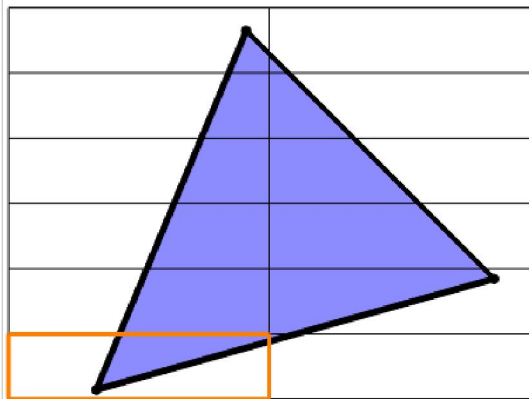


AVX register

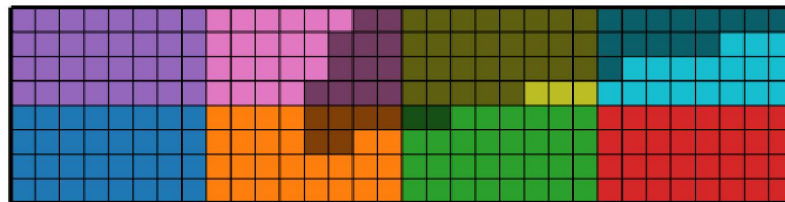
# Shuffle mask

- **Shuffle mask to form better shaped tiles**

- Before: each SIMD-lane is a scanline
- After: each SIMD-lane is a 8x4 tile



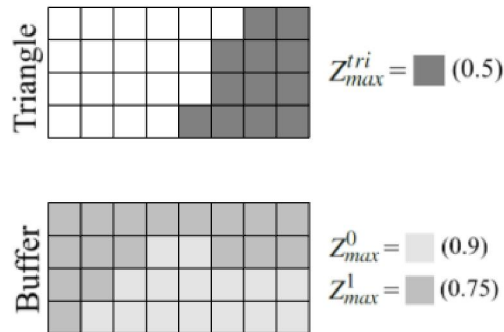
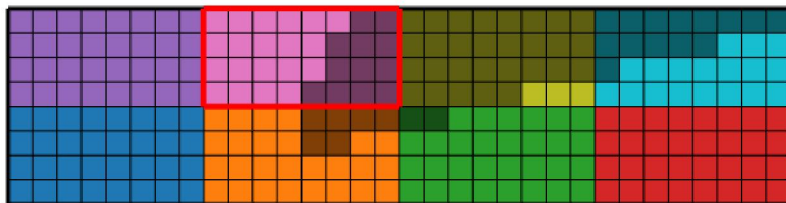
Coverage mask



AVX register

# Masked Depth Buffer Update

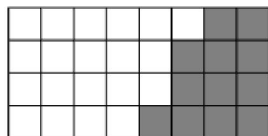
- **Masked z update similar to previous work [AHAM15]**
  - Optimized for AVX and software implementation
  - Less accurate than original, more dependent on render order
  - Easier to control render order than for HW culling
- **Input for an 8x4 tile**
  - Tri: Coverage mask (32b) + Zmax value (32b float)
  - Buffer: Selection mask (32b) + 2 Zmax values (2x32b float)



# Masked Depth Buffer Update

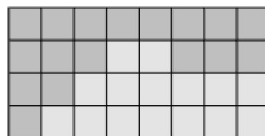
- $Z_{max}^1$  is the working layer
  - Updated as:  $\max(Z_{max}^1, Z_{max}^{tri})$
  - Mask is updated using bitwise or
- $Z_{max}^0$  is the reference layer
  - Whenever working layer mask is full, overwrite reference layer
  - Clear working layer

Rasterized triangle



$$Z_{max}^{tri} = \text{■} (0.5)$$

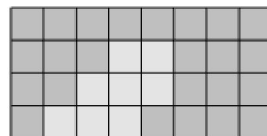
Buffer entry



$$Z_{max}^0 = \text{■} (0.9)$$

$$Z_{max}^1 = \text{■} (0.75)$$

Updated Buffer entry

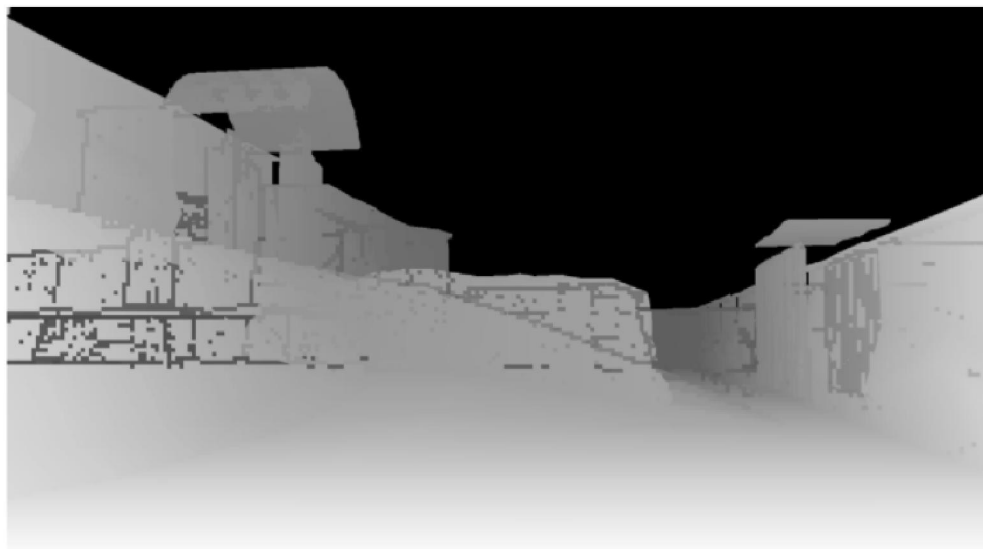


$$Z_{max}^0 = \text{■} (0.9)$$

$$Z_{max}^1 = \text{■} (0.75)$$

# Update Heuristic Results

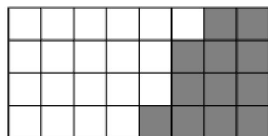
- **Silhouettes can leak through geometry**
  - Reason: partial working layer contaminates foreground layer, which would otherwise completely overwrite the tile



# Revised Update

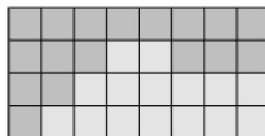
- **Discard working layer if drawing a new object**
  - Throw away partial data avoid contaminating layers in front
  - How to know if we begin drawing a new object?
- **Discard heuristic**
  - If  $Z_{max}^1 - Z_{max}^{tri} > Z_{max}^0 - Z_{max}^1$ , discard working layer
  - Avoids fixed threshold value

Rasterized triangle



$$Z_{max}^{tri} = \text{■} (0.5)$$

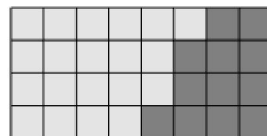
Buffer entry



$$Z_{max}^0 = \text{□} (0.9)$$

$$Z_{max}^1 = \text{■} (0.75)$$

Updated Buffer entry



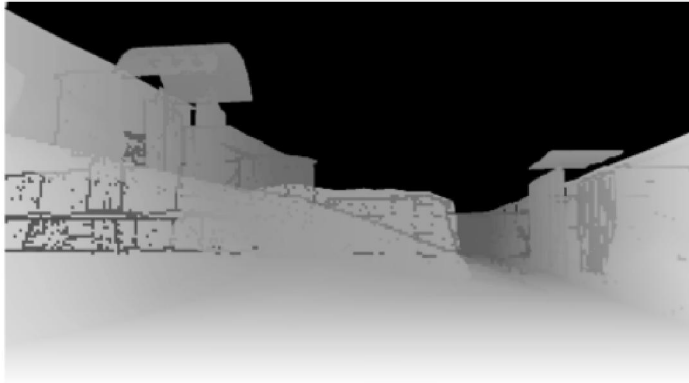
$$Z_{max}^0 = \text{□} (0.9)$$

$$Z_{max}^1 = \text{■} (0.5)$$

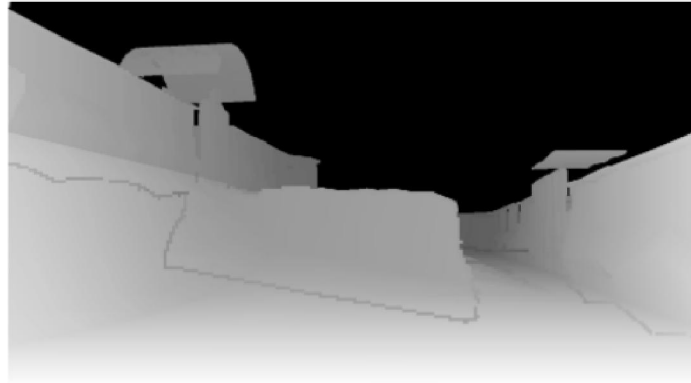


# Update Heuristic Results

---



No discard



Discard heuristic

---

# Results

# Results

## Intel Occlusion Culling Sample

- **Integrated in Intel occlusion culling sample**
  - Uses low-poly occluder meshes
  - Two pass occlusion culling (rasterize occluders, perform queries)
  - Contains an AVX2 optimized version of the HiZ algorithm
  - Integrated our algorithm making minimal changes



# Results

## Intel Occlusion Culling Sample

- **Algorithm timing breakdown**

- Clear: Clearing the depth buffer
- Geom: Transform & project geometry
- Rast: Triangle setup & occluder rasterization
- Gen: Compute hierarchical z buffer from full resolution z buffer
- Test: Perform occlusion queries

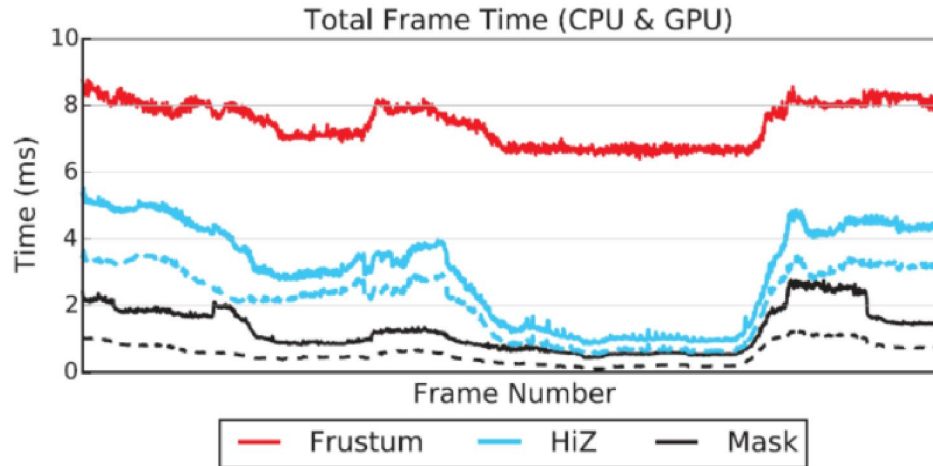
	Clear	Geom	Rast	Gen	Test	Total
HiZ	377	196	2145	509	278	3505
Mask	23	194	584	0	255	1056

**16x**                      **3.7x**

# Results

## Intel Occlusion Culling Sample

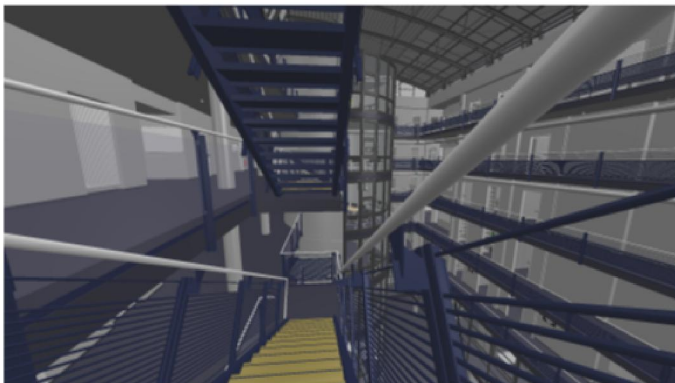
- Performance comparison for camera animation



# Results

## Standalone framework

- **Standalone engine tailored for our algorithm**
  - One pass: interleaving occluder rasterization and occlusion queries
  - Early exit: don't perform occlusion culling in occluded regions
  - Modified version of the hierarchical z buffer (HiZ) algorithm



**MPI Informatics Building**  
Mesh: 72 MTris, Occluder: 143 KTris

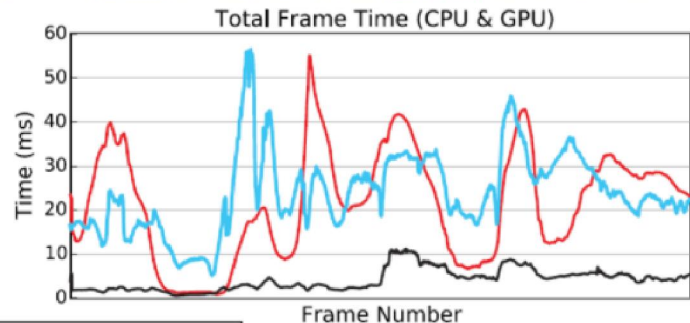
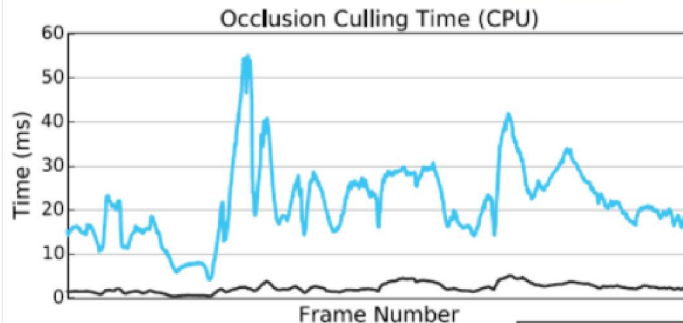
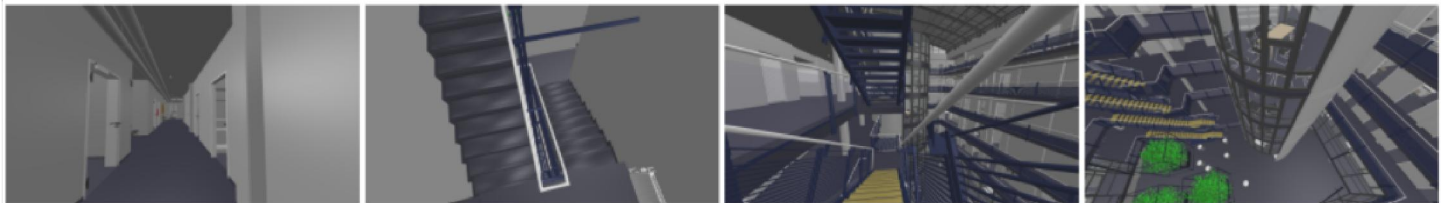


**Rungholt**  
Mesh: 7 MTris, Occluder: 7 MTris

# Results

## MPI Informatics Building

- Performance during camera flythrough



— Frustum — HiZ — Mask

# Rungholt

- Live demo



# Conclusion

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- **Efficient algorithm for rasterizing occlusion buffers**
  - More than 3x better performance than previous work
  - Can be integrated tightly with traversal algorithm (low latency)
  - Very accurate culls 98% of all triangles culled by hierarchical z buffer
- **Future work**
  - Efficient multi-threading
  - Better update heuristics for masked z buffer
  - GPU implementation

# Thank you

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- **Source code available**
  - [www.github.com/GameTechDev/MaskedOcclusionCulling](https://www.github.com/GameTechDev/MaskedOcclusionCulling)
- **Questions**