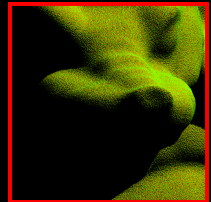
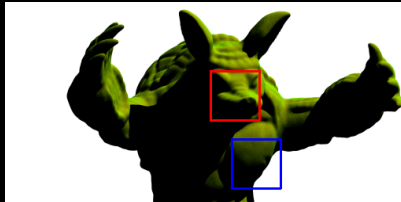
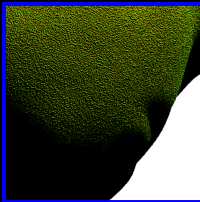


Representing Appearance and Pre-filtering Subpixel Data in Sparse Voxel Octrees

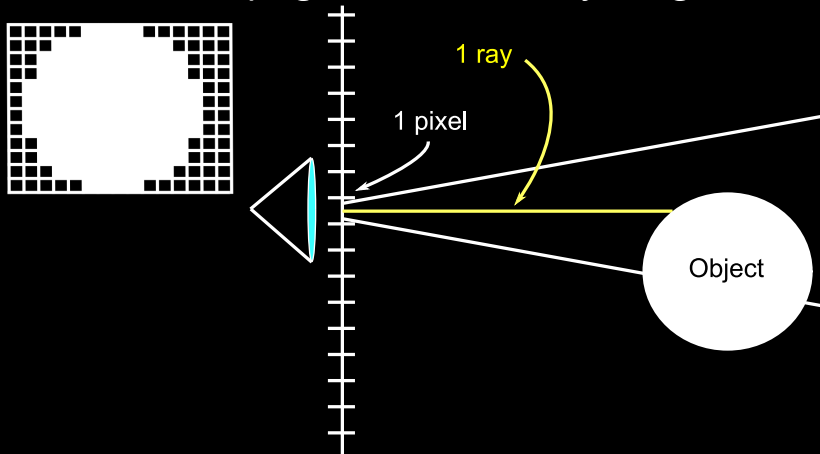
HPG 2012

Eric Heitz Fabrice Neyret

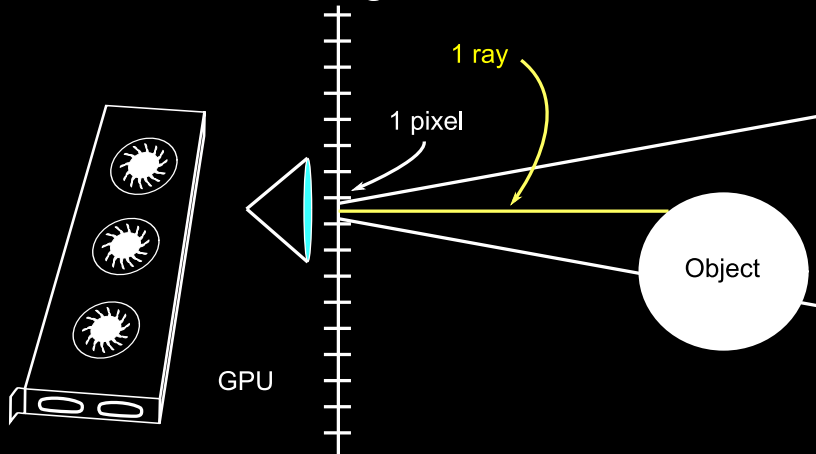
INRIA Rhône-Alpes – Laboratoire Jean Kuntzmann (Université de Grenoble and CNRS)



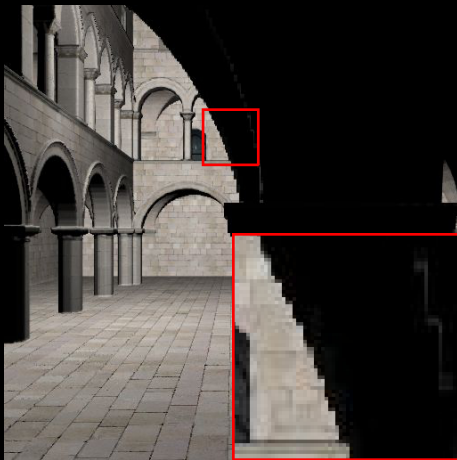
Pixel sampling : rasterization or raytracing..



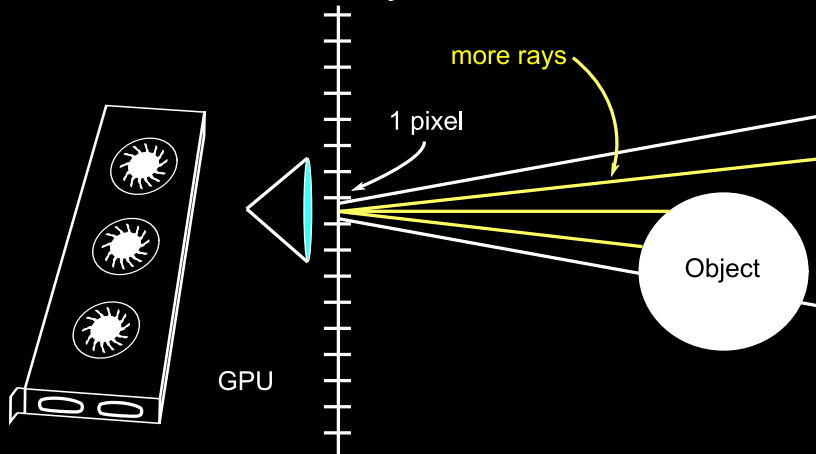
..running on the GPU



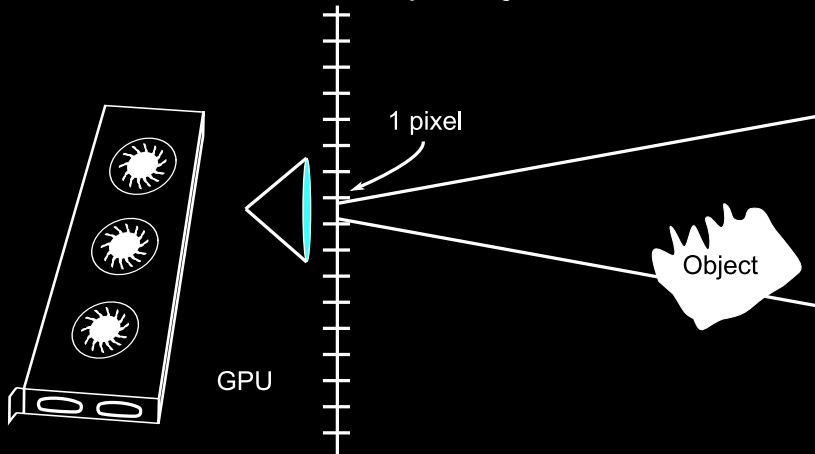
Sampling with only one ray produces aliasing

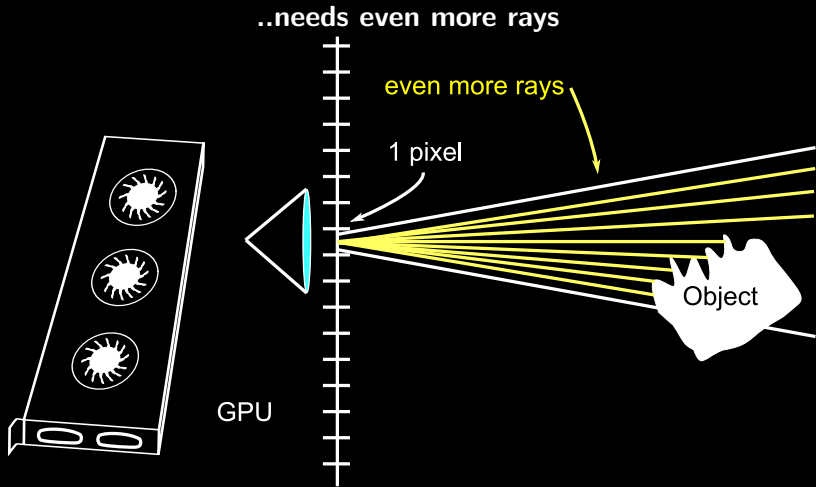


Cast more ray to anti-aliase..

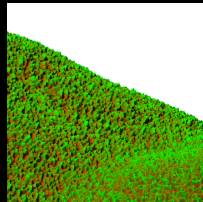
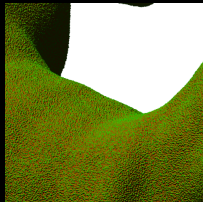


A more complex object..

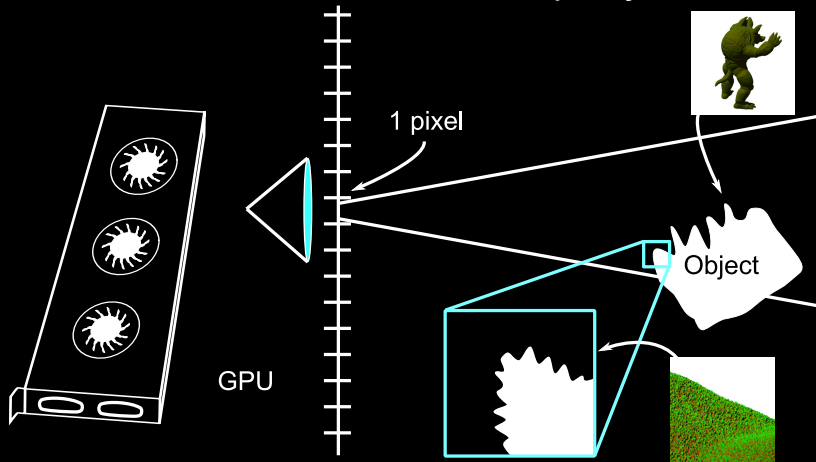




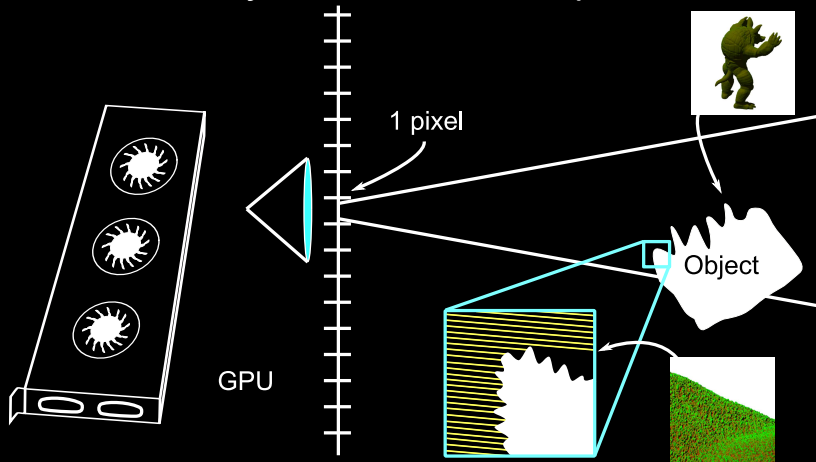
Still more details, more complexity



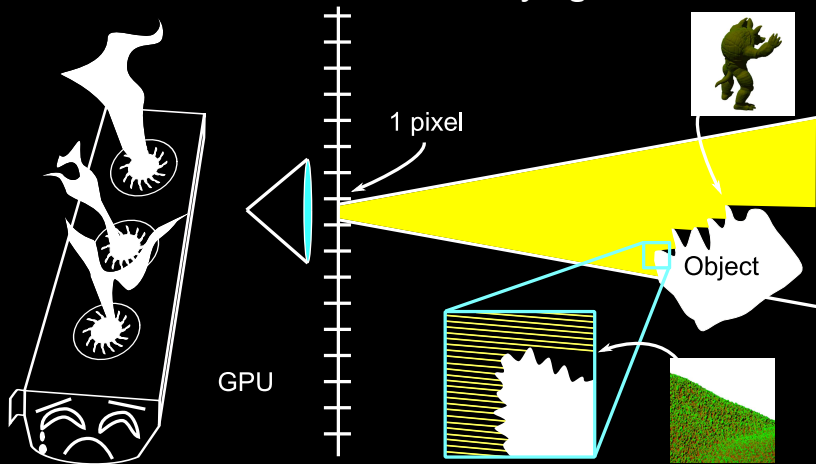
Still more details, more complexity



Every detail needs to be sampled



Unaffordable even for a very big GPU



Scalability in Raytracing

Scalable rendering algorithms

- ▶ only 1 ray per pixel instead of oversampling

Scalable rendering representations

- ▶ Don't adapt yourself to the scene,
have the scene adapt to you

Important Features

- ▶ Pre-filtered representations
- ▶ Interpolation through space and scale

Local Illumination Equation

Integration of the surface A over the pixel footprint

$$I = \frac{\int_A E_i a \rho_{v,l} V_l V_v \mathbf{n} \cdot \mathbf{l} \mathbf{n} \cdot \mathbf{v} dp}{\int_A V_v \mathbf{n} \cdot \mathbf{v} dp}$$

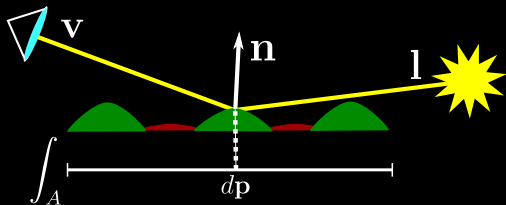
with

E_i incoming radiance

a material albedo

$\rho_{v,l}$ BRDF

V_v, V_l visibilities



Mipmapping Approximation

The terms in the integral are **not correlated**

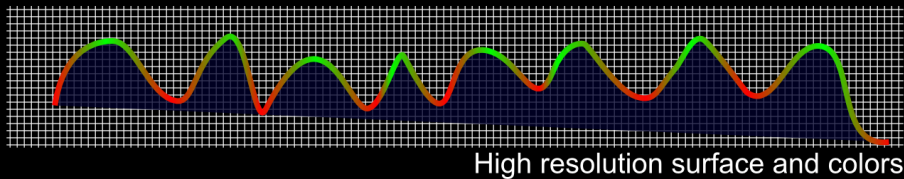
→ they can be **separately integrated**

$$I = \frac{\int_A E_l a \rho_{v,l} V_l V_v n_l n_v d\mathbf{p}}{\int_A V_v n_v d\mathbf{p}}$$

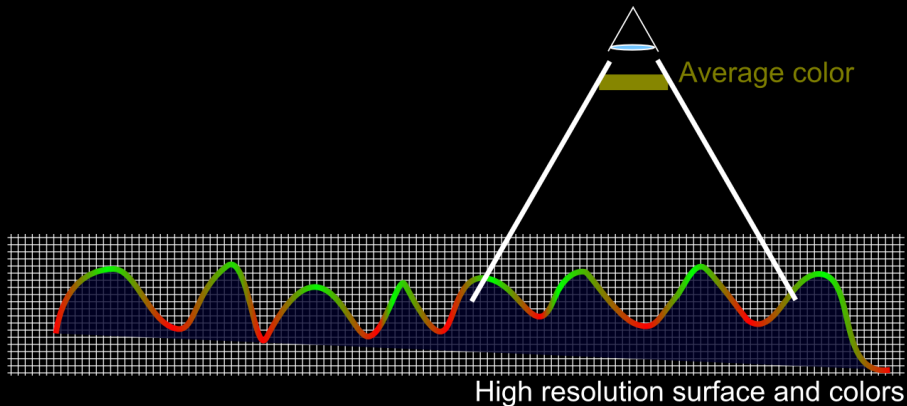
becomes

$$I \approx \frac{\int_A E_l d\mathbf{p}}{\int_A d\mathbf{p}} \frac{\int_A a d\mathbf{p}}{\int_A d\mathbf{p}} \frac{\int_A \rho_{v,l} n_l d\mathbf{p}}{\int_A d\mathbf{p}} \frac{\int_A V_l d\mathbf{p}}{\int_A d\mathbf{p}}$$

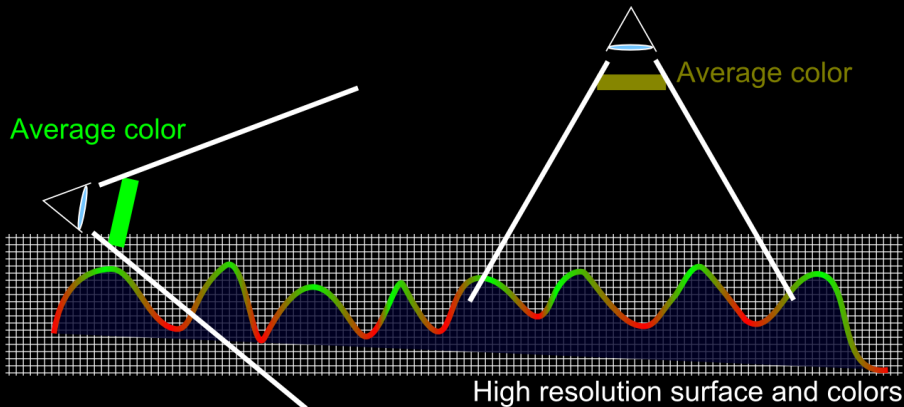
The effect of correlation



The effect of correlation

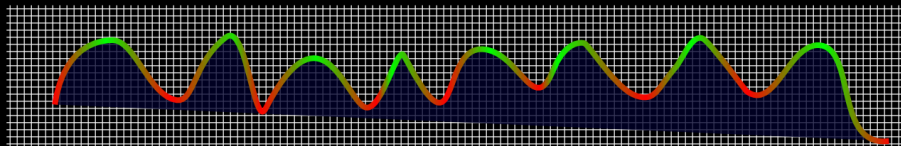


The effect of correlation

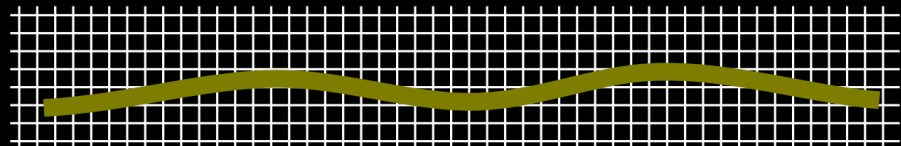


$$\int a V_v \neq \int a \int V_v$$

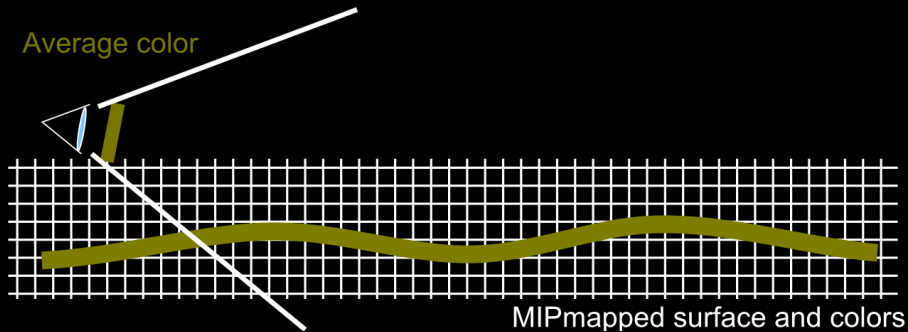
The effect of correlation



MIPmapping process



The effect of correlation



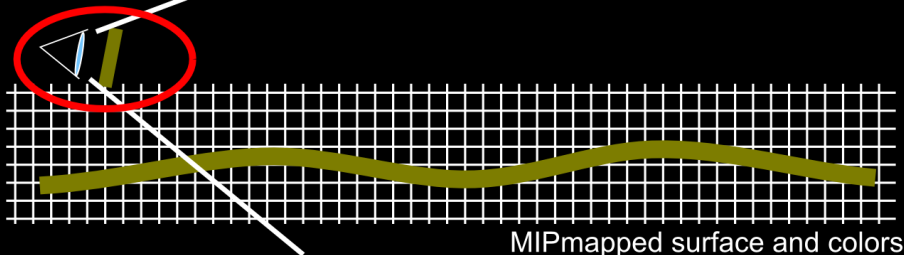
The effect of correlation

Masking effects are lost
with separate
MIPmapping



Visibility has to be
taken into account
in the pre-filtering
process !

Average color



Many real-world surfaces show such correlations



Important Features

- ▶ **Pre-filtered representations**
 - ▶ **Mipmapping does not work with correlations**
- ▶ **Interpolation through space and scale**

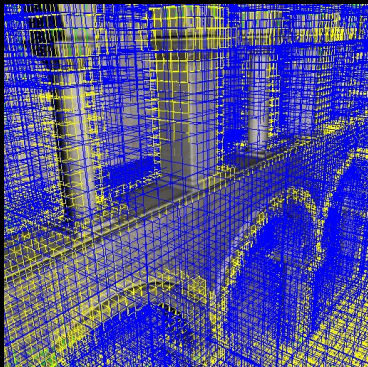
Important Features

- ▶ **Pre-filtered representations**
 - ▶ **Mipmapping does not work with correlations**
- ▶ **Interpolation through space and scale**
 - ▶ **Meshes do not filter properly**
 - ▶ **Meshes have parametrization and topological problems**

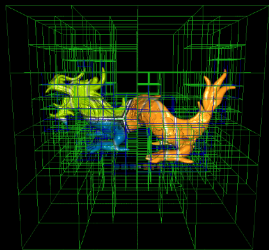
Sparse Voxel Octrees (SVO)

Properties

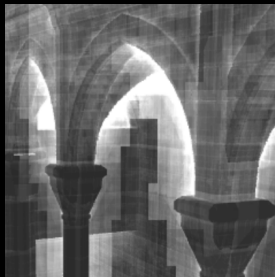
- ▶ Spatial organization
- ▶ No parametrization problem
- ▶ LoD representation
- ▶ GPU implementation



Previous Work

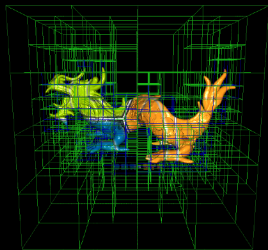


GigaVoxels [CNLE09]



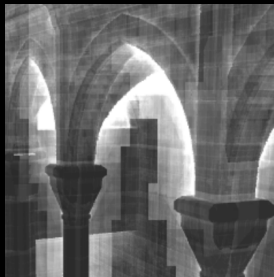
Efficient Sparse Voxel Octrees [LK10]

Previous Work



GigaVoxels [CNLE09]

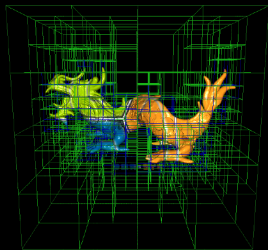
- Interpolation



Efficient Sparse Voxel Octrees [LK10]

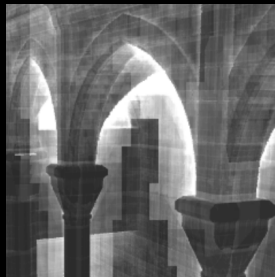
- No interpolation

Previous Work



GigaVoxels [CNLE09]

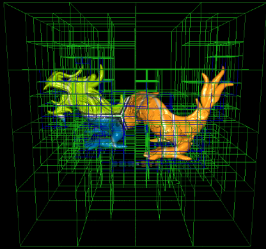
- Interpolation
- Volume rendering



Efficient Sparse Voxel Octrees [LK10]

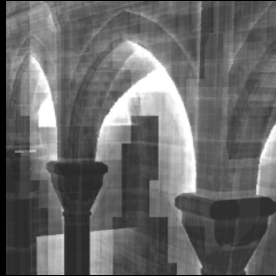
- No interpolation
- Surface rendering

Previous Work



GigaVoxels [CNLE09]

- Interpolation
- Volume rendering
- Pre-filtering
 - Material pre-filtering
 - No normal pre-filtering
 - No visibility pre-filtering



Efficient Sparse Voxel Octrees [LK10]

- No interpolation
- Surface rendering
- No pre-filtering
 - No material pre-filtering
 - No normal pre-filtering
 - No visibility pre-filtering

Our Sparse Voxel Octree Model

- **Interpolation** : GigaVoxels [CNLE09] data-structure

Our Sparse Voxel Octree Model

- Interpolation : GigaVoxels [CNLE09] data-structure

Contributions

- **Surface-based representation** : 1. Macro-surface representation

Our Sparse Voxel Octree Model

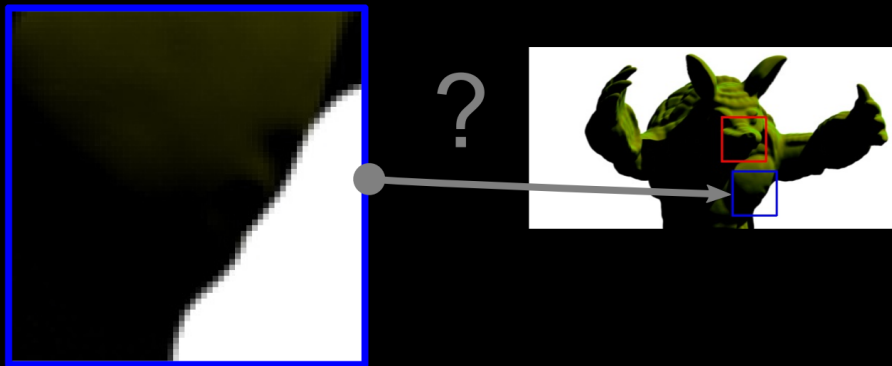
- Interpolation : GigaVoxels [CNLE09] data-structure

Contributions

- **Surface-based representation** : 1. Macro-surface representation
- **Pre-filtering (bottom-up build)** : 2. Micro-surface representation
 - Material pre-filtering
 - Normal pre-filtering
 - Visibility pre-filtering

- 1. Macro-surface model**
2. Micro-surface model

How to render anti-aliased surfaces ? (with 1 ray per pixel)

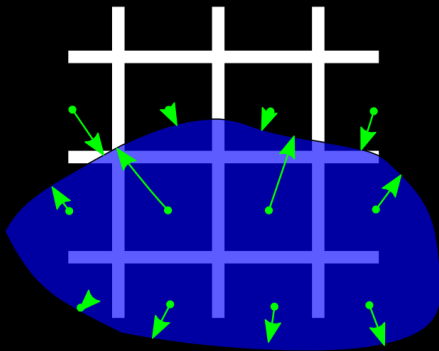


Rendering with Subpixel Occlusion Distributions

- ▶ The A-buffer, an antialiased hidden surface method
[Carpenter 84]
- ▶ Tracing ray differentials
[Igehy 99]

Surface Representation

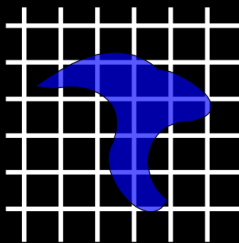
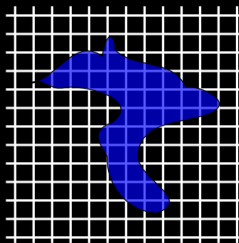
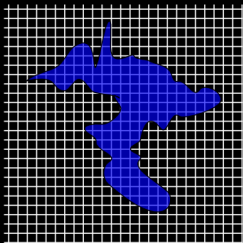
A signed distance field keeps the subvoxel surface position



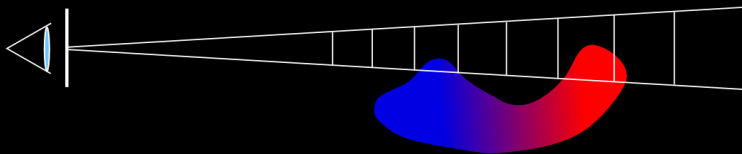
Surface Representation

We build a LoD surface representation

At runtime, the pixel footprint matches the size of a voxel

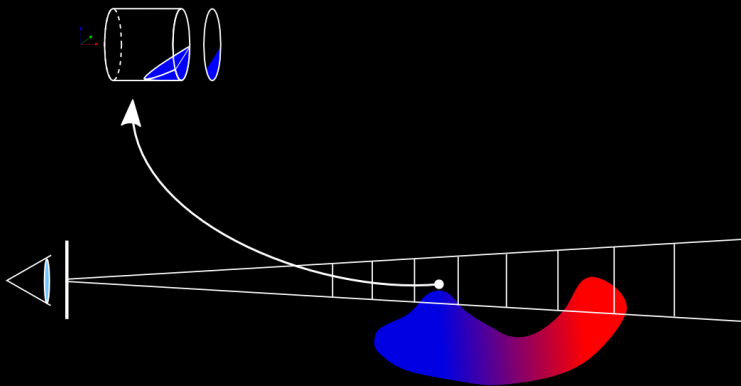


Differential Cone Tracing Scheme

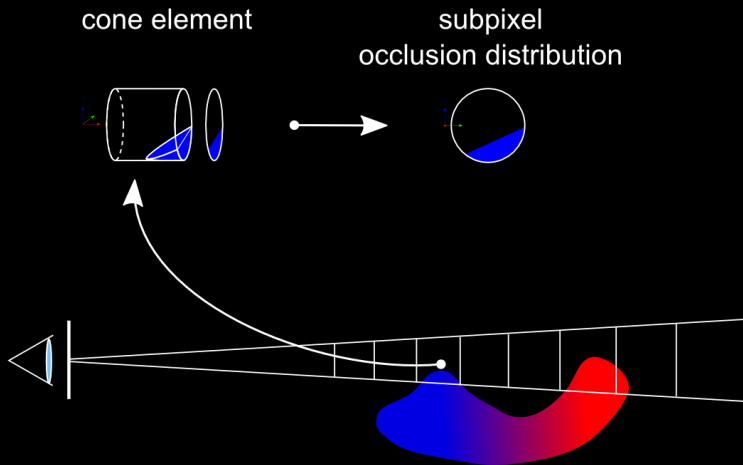


Differential Cone Tracing Scheme

cone element



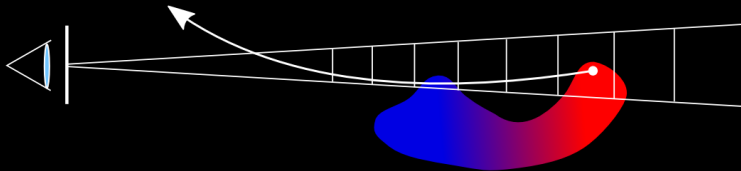
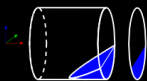
Differential Cone Tracing Scheme



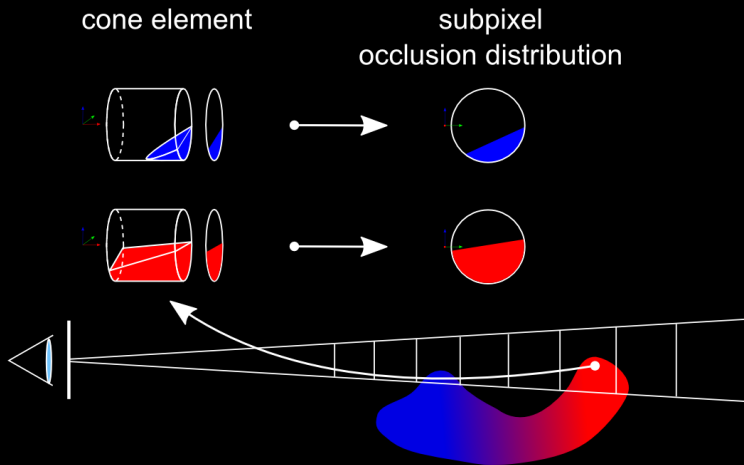
Differential Cone Tracing Scheme

cone element

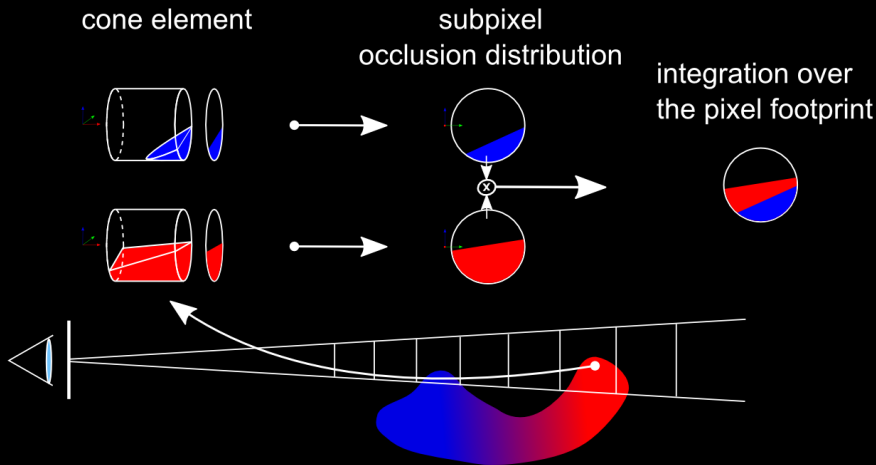
subpixel
occlusion distribution



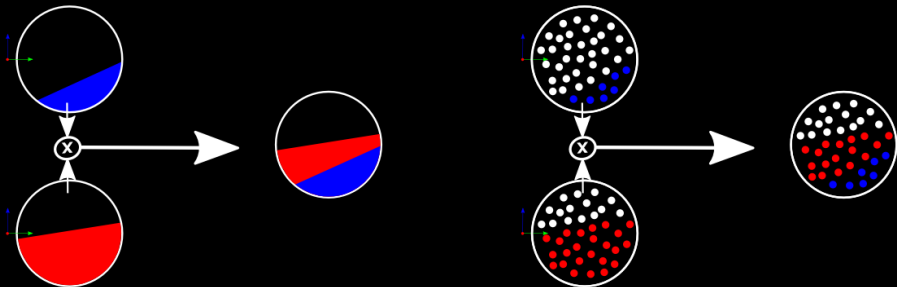
Differential Cone Tracing Scheme



Differential Cone Tracing Scheme



We represent the subpixel occlusion distribution with pre-computed binary mask and combine them in a A-buffer way

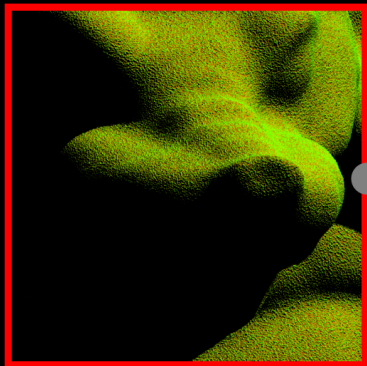


Results

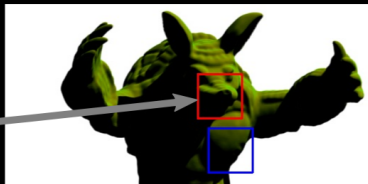
Results

1. Macro-surface model
2. **Micro-surface model**

How to represent complex details from far-away ?



?



$$I = \frac{\int_A E_l a \rho_{v,l} V_l V_v n_l n_v dp}{\int_A V_v n_v dp}$$

A Hierarchy of Scales

- ▶ Anisotropic reflection models

[Kajiya 85]

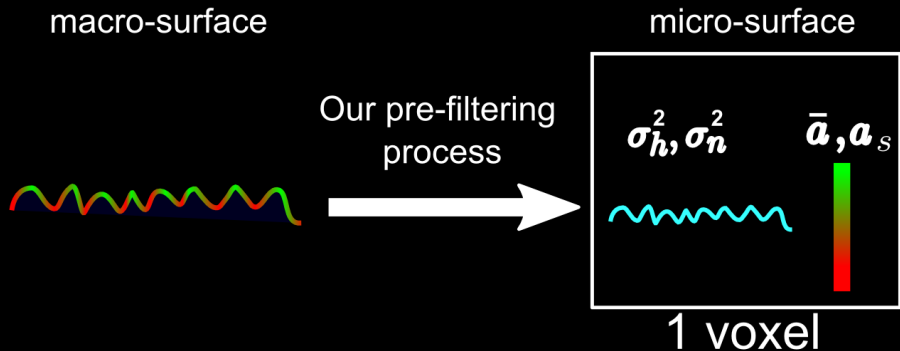
- ▶ Normal distribution functions and multiple surfaces

[Fournier 92]

- ▶ Smooth transitions between bump rendering algorithms

[Becker and Max 93]

Pre-filtering Process



Normal Pre-filtering Strategy



*



=



Gaussian slope statistics
of the micro-surface

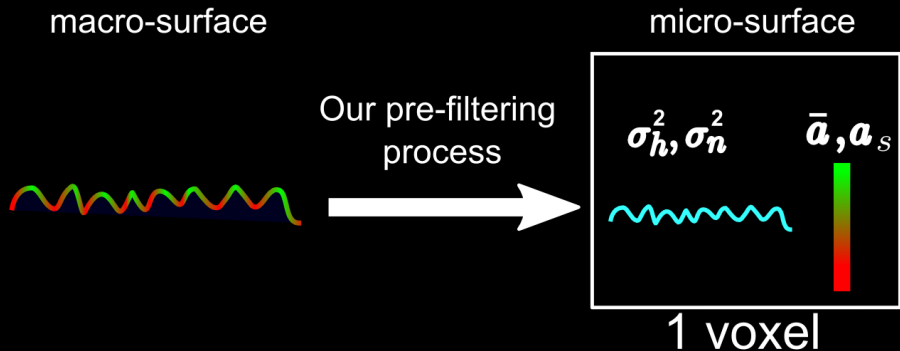
ground material roughness
(BRDF with Gaussian distribution)

macro-BRDF
used for shading

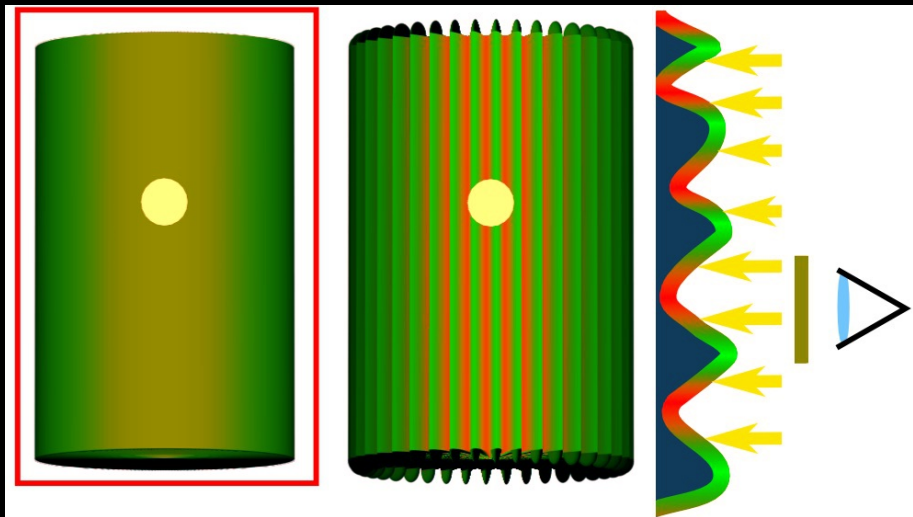


Normal Pre-filtering Result

Pre-filtering Process



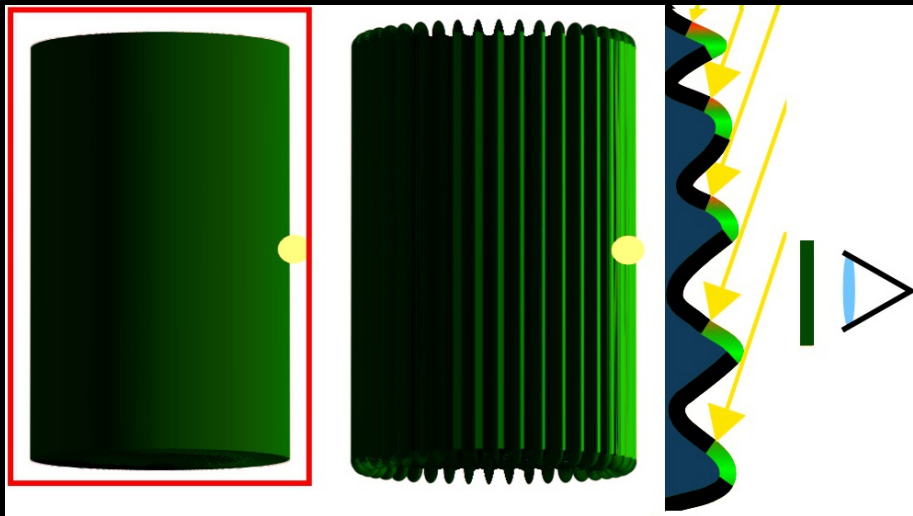
Pre-filtering Masking Effects



| Our micro-surface model || Macroscopic behaviour |

2. Micro-surface model

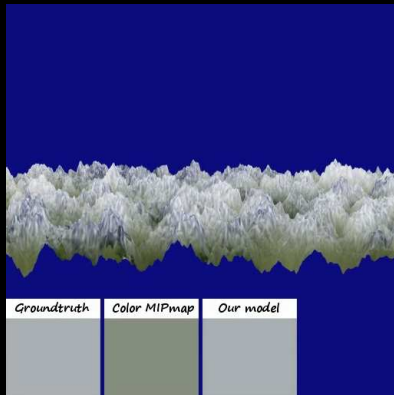
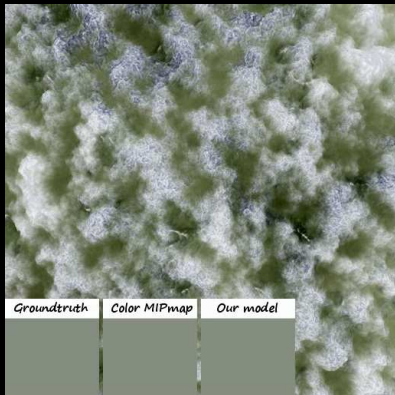
Pre-filtering Shadowing Effects



| Our micro-surface model || Macroscopic behaviour |

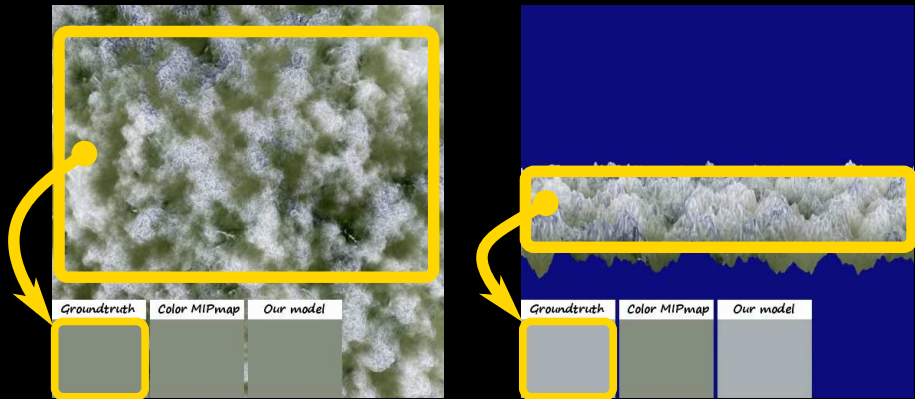
2. Micro-surface model

Validation on Real Textures



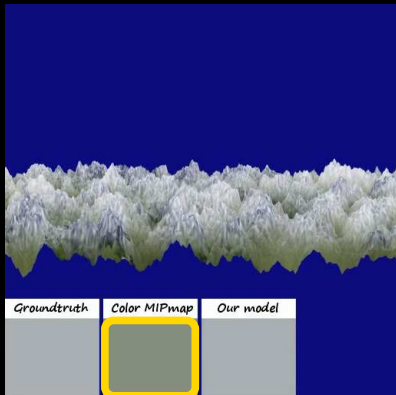
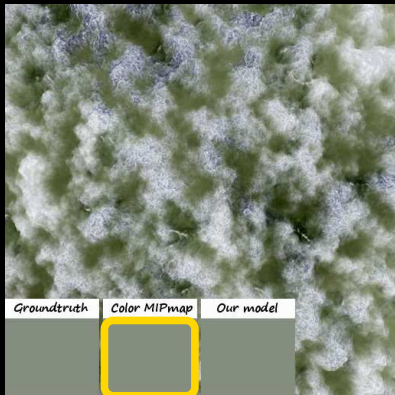
A real-world texture
showing strong correlation between colors and heights

Validation on Real Textures



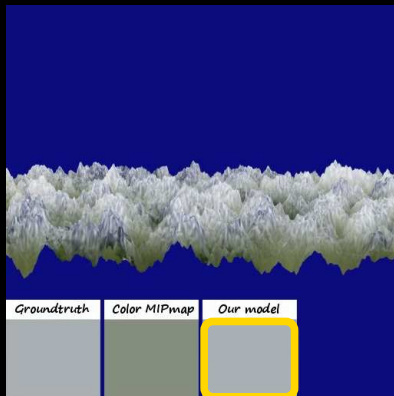
The groundtruth is the average visible color
It is view-dependent

Validation on Real Textures



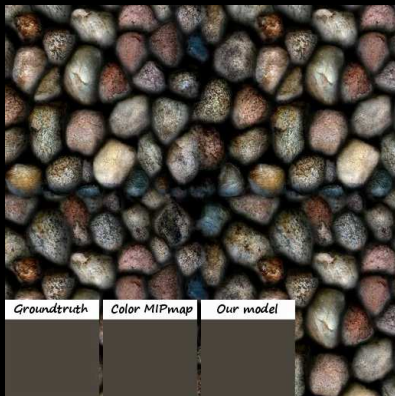
The mipmapped color is the average of the texture
It is NOT view-dependent

Validation on Real Textures



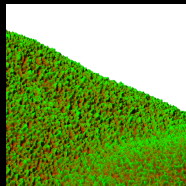
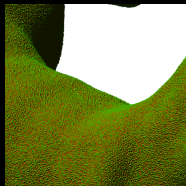
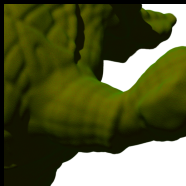
Our model is view-dependent
It is a better approximation than mipmap

Validation on Real Textures



Our model is view-dependent
It is a better approximation than mipmap

Performances



fps
 $\mu\text{s}/\text{pix}$

57
0.26

37
0.13

25
0.22

19
0.32

The timing per covered pixel is consistent through scales

Conclusion

Properties of our model

- ▶ Scalable
- ▶ Accurate appearance pre-filtering
- ▶ Seamless LoD transition

- ▶ Differential cone tracing scheme
 - works also with implicit distance fields
- ▶ Micro-surface representation
 - works also with textures and height-maps

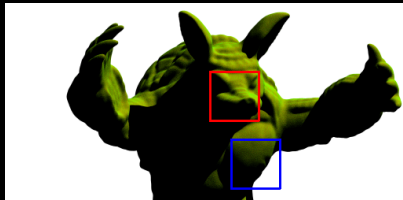
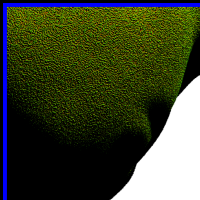
Future Work

Limitation of our approach

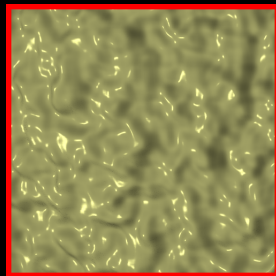
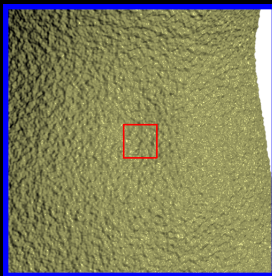
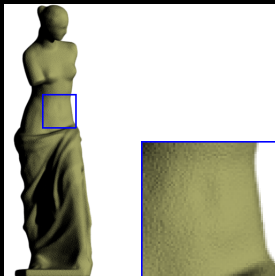
- ▶ B-rep objects

Other desirable features

- ▶ Semi-transparent material, volume rendering
- ▶ Pre-filtering other kinds of correlation

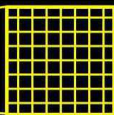
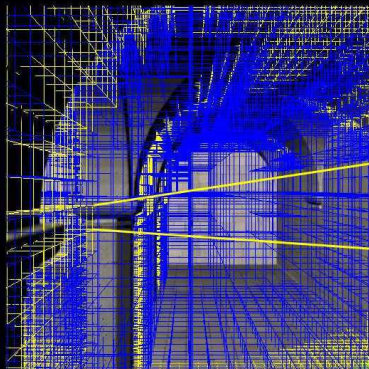


Thank you for your attention!

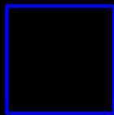


The GigaVoxels [CNLE09] octree structure stores voxel bricks at each node instead of only one voxel

→ hardware interpolation possible



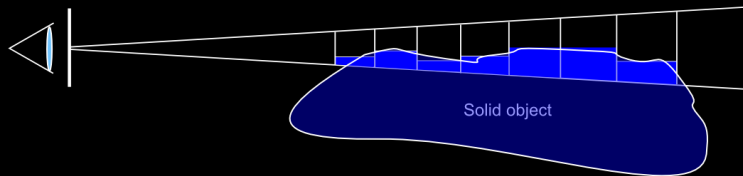
= 8^3 voxel brick

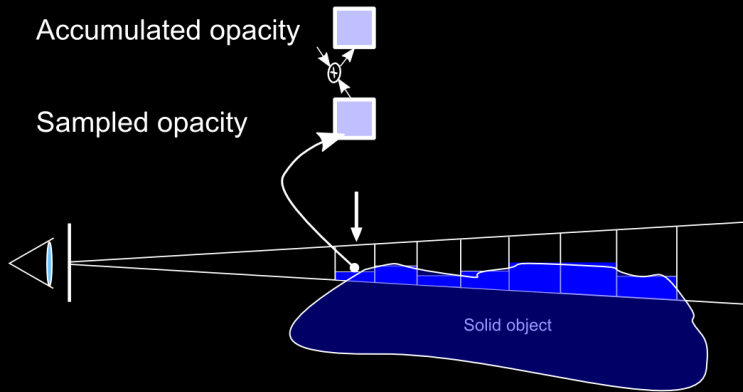


= empty node

Accumulated opacity

Sampled opacity





Accumulated opacity

Sampled opacity

Solid object

