

# A Patch-Based Bit Mask Filtering Method for Micropolygon Rasterization

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### **Problem**

Sampling hit rates in the rasterization stage are low when the screen coverage of triangles are small, especially for micropolygons.

### **Previous work**

- ➤ Hierarchical tiling
  - Quickly find boundaries and tick out inside tiles [Greene, 1996]
- ➤ Data parallel processing
  - Exploit parallelism across triangles [Fatahalian et al., 2009]

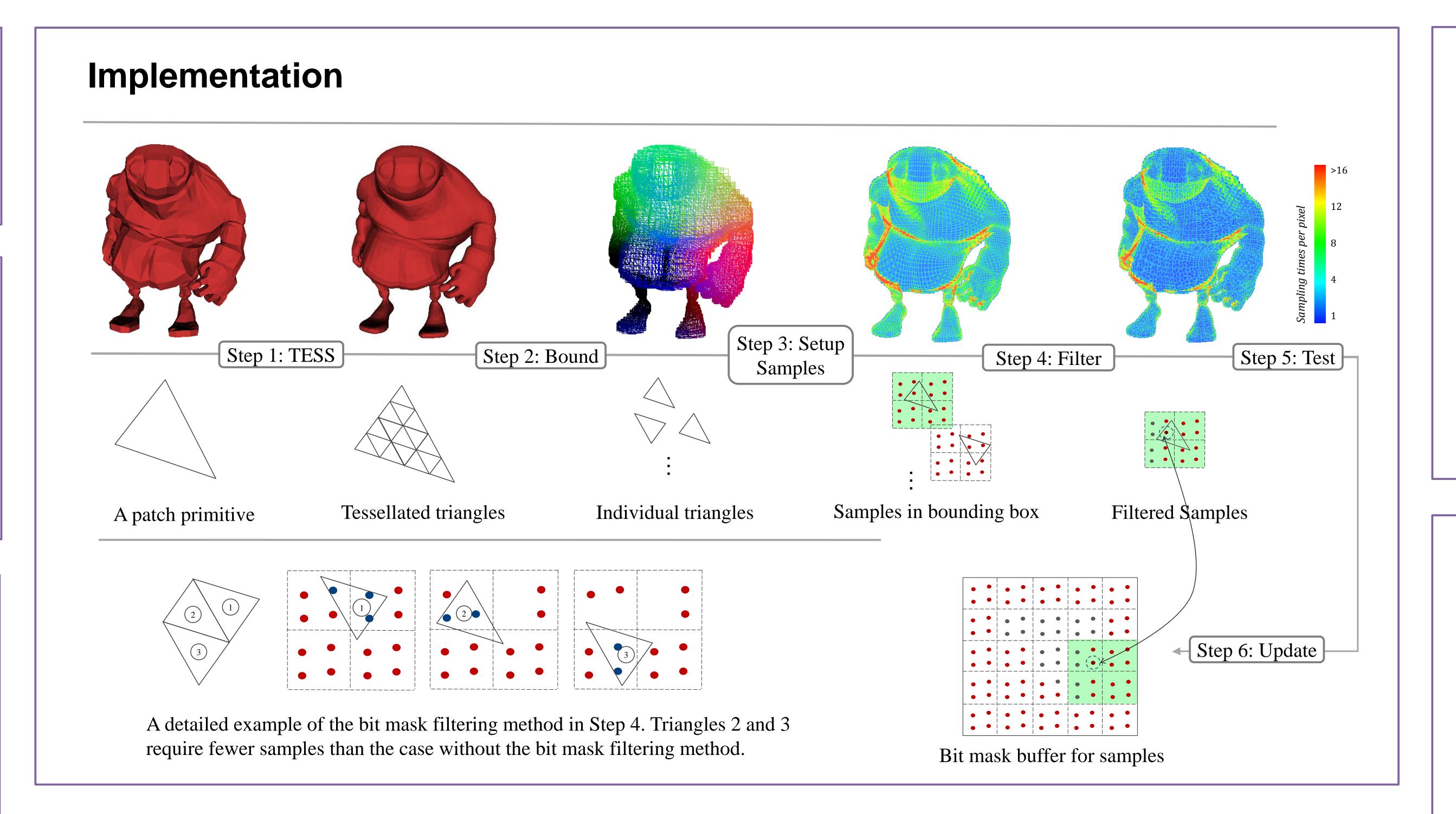
# Challenges

Traditional tiling methods to improve sampling hit rates do not work when the triangle sizes are very small. There are no quick "accepted as hit" tiles inside small triangles.

The data parallel method does not aim to solve the sampling hit rate problem and it requires that the input polygons be roughly identical in size, shape, and orientation.

# Our method

- ➤ Observation: A typical scene is usually covered by flat meshes without overlap. In such a case, each screen sample lays in only one triangle. However, the same sample is often calculated many times.
- Our method takes the tessellated triangles from a patch as a unit, and exploits locality of these clustered triangles.
- A bit mask is used to filter the hit samples from the point-in-polygon tests. These hit samples in one triangle are considered to be redundant samples for its neighborhood triangles.
- We examined different sub-pixel sized micropolygons and pixel sized small triangles to analyze their efficiency under different configurations.



#### >Experimental setup **Evaluation** Subdivision method: The Catmull subdivision method is Locality evaluation Stamp size evaluation employed. It generates four sub-triangles in one round. ► <u>Model used</u>: 3k triangles bigguy model, 12 triangles cube model, and 2.8k triangles monster frog model are used in the **Bigguy model under different stamp sizes** Bigguv model under different level of subdivision ▶ <u>Platform</u>: CPU is used for the method simulation. GPU is used Subdivision: 2 7.00% for parts of the visualization. 20.00% Conventional N1 Conventional S4 ◆ The bigger stamp size is not suitable for micropolygons, here a stamp is defined as a screen tile measured by pixel size. Besides, since big stamps cover more areas, they decrease benefits from locality. S: Stamp size **Triangle size (measured by screen pixel)** Reduced redundant computing Cube model under different level of subdivisions Bigguy model under different configurations 18.00% 16.00% 14.00% 12.00% Conventional N6 Redundant sampling of the monster frog model rendered under different Proposed M1 T1 Proposed M1 T4 4.00% -Proposed M4 T1 Proposed M4 T4 ◆ When the multi-sampling rate is higher, the number of Proposed M16 T1 reduced samples will also increase. Proposed M16 T4 ◆ Although bigger stamps result in more reduced samples, ◆ As one patch contains more triangles in the same area, the the wasted samples are also significant. filtering effect becomes significant. The cube model has more M: Multi-sampling rate flat areas, thus gains better optimization.

## Conclusions

- ➤By testing various sized small triangles, we show that without the proposed method, the bound and test algorithm for micropolygons results in low sampling hit rates.
- The proposed method works best for flat areas with intensively small triangles. As locality increases, higher sampling hit rates can be gained.
- Although the point-in-polygon test does not take such a long time as shading, redundant sampling tests can increase 10 times per sample location as triangle size shrinks.
- If the projected triangles are too long and/or too narrow in the screen space, the performance improvement achieved by the proposed method is still limited.

### **Future work**

- Considering its hardware cost, we must design a smarter bit mask buffer mechanism to use a small amount of memory.
- The overhead of the bit mask operation is required to evaluate, since rasterization should keep simple to achieve efficiency.
- The idea should be extended to support motion blur and depth of field where more samples are required.
- ➤ More study is necessary for patch level parallel rasterization. Comparisons with the triangle level parallelism and the current GPU rasterization could be more interesting.

# References

K. Fatahalian, E. Luong, S. Boulos, K. Akeley, W. R. Mark, and P. Hanrahan, "Data-parallel rasterization of micropolygons with defocus and motion blur," in HPG 2009. ACM, 2009, pp. 59–68.

N. Greene, "Hierarchical polygon tiling with coverage masks," in SIGGRAPH 1996. ACM, 1996, pp. 65–74.

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