Improving SIMD Efficiency for Parallel Monte Carlo Light Transport on the GPU





Outline

Introduction

- Path Tracing
- Bidirectional Path Tracing
- Metropolis Light Transport
- Results
- Demo



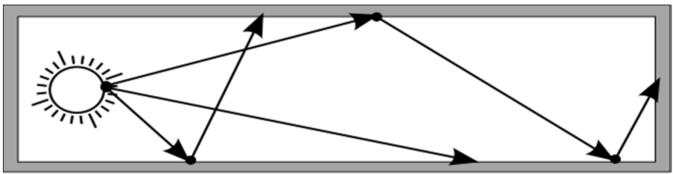
Parallel MC Rendering

- Monte Carlo rendering embarrassingly parallel
- Generate many samples in parallel
- Not so trivial for wide SIMD architectures
- Samples have stochastic sample length
- Uneven sample workload
- Incoherent execution flow
- Low SIMD efficiency



Random Walk

• PT and BDPT use random walks

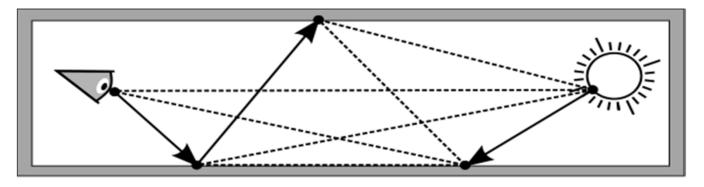


- Walk is terminated using Russian roulette
- Stochastic path lengths
- ~33% active threads per GPU warp
- Upper bound on SIMD efficiency



Bidirectional Connections

BDPT fully connects two random walks



- Number of connections is quadratic in average random walk length
- ~17% active threads per GPU warp
- Upper bound on SIMD efficiency



Contributions

- Improving average SIMD efficiency
 - Random walk phase:
 - Combining stream compaction and sample regeneration
 - Bidirectional connect phase:

Evaluating all **connections** from all samples **in parallel**

Implement MLT on top of BDPT on the GPU



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In-Place Sample Regeneration

- Proposed by Novak et al.
- Regenerate after each extension
- Restart all terminated samples in-place
- Advantage:
 - Improves SIMD efficiency during sample extension and connection
- Disadvantage:
 - Low SIMD efficiency during regeneration
 - ~30% active threads per GPU warp

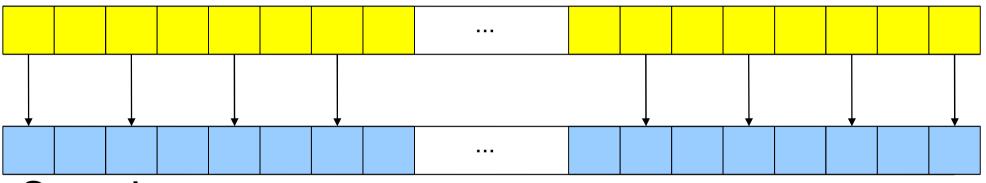


- Remove terminated samples from the stream using stream compaction
- Short stream length may reduce GPU utilization
- Regenerate terminated samples at the end of the sample stream



Initialize sample stream

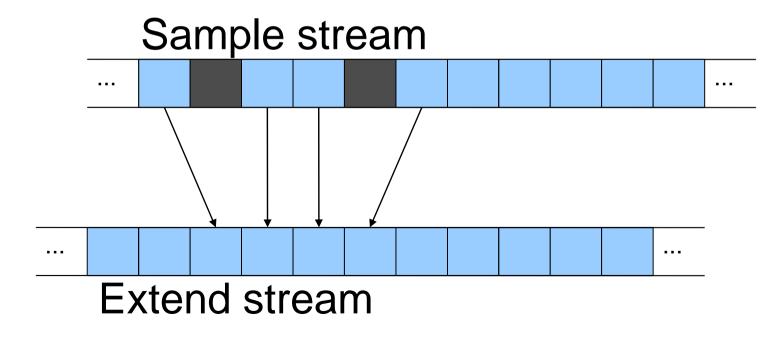
Generate stream



Sample stream

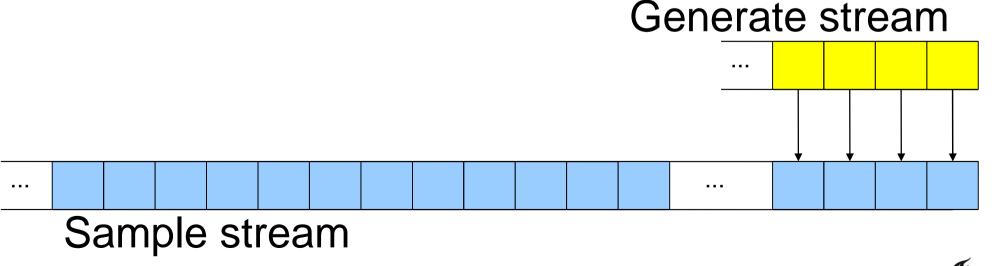


- Extend all samples with next path vertex
- Some samples terminate
- Compact output stream





- Output stream becomes next sample stream
- Regenerate new samples at the end





Advantages

- High SIMD efficiency during extension and connection
- High SIMD efficiency during regeneration
- Fixed size sample stream
- Regenerated samples lie side-by-side
- Primary rays benefit from primary ray coherence
- ~20% speedup over in-place sample regeneration



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Bidirectional Path Tracing

- Improve SIMD efficiency during random walk
 - Combine stream compaction and regeneration
- Improve SIMD efficiency during connection
 - Evaluate all bidirectional connections in parallel

- Algorithm is divided in random walk and connect phase
- Phases execute repeatedly one after the other



• Initialize eye and light path stream



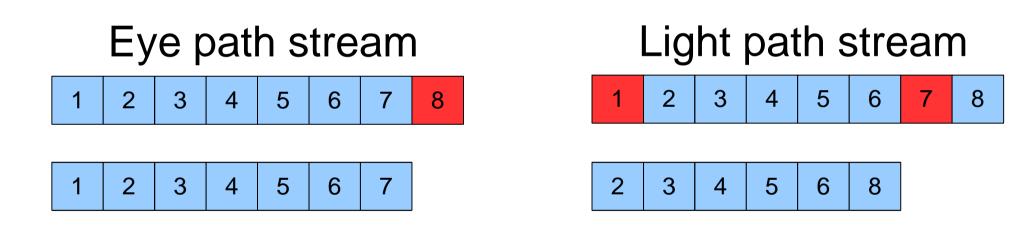


- Extend all paths with one vertex
- Some paths terminate

Eye path stream Light path stream

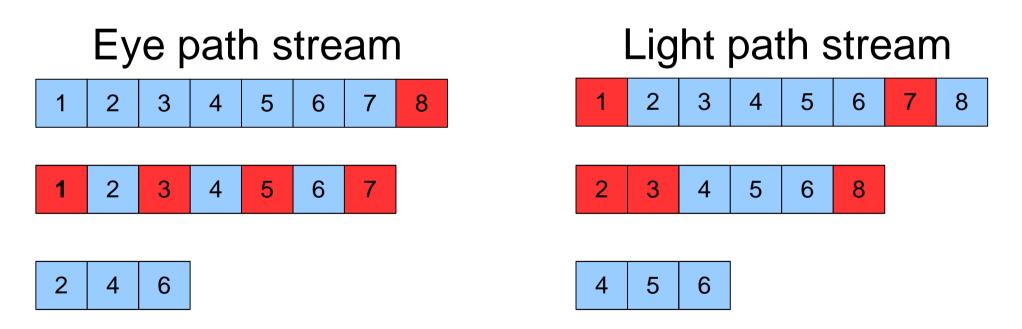


Compact path streams



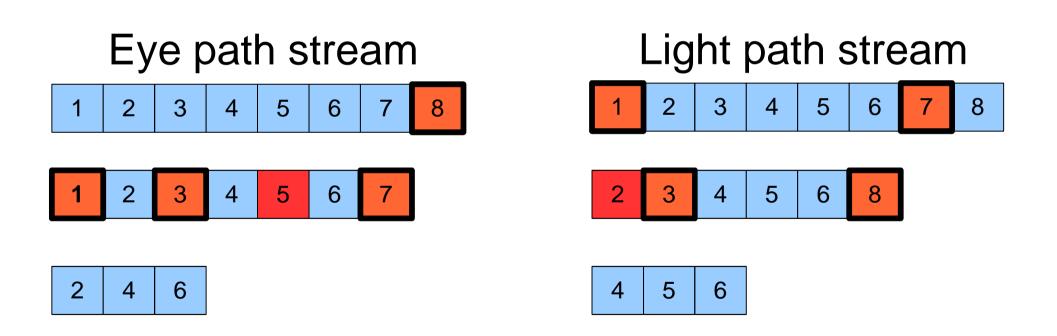


- Repeat extend and compact
- Postpone regeneration



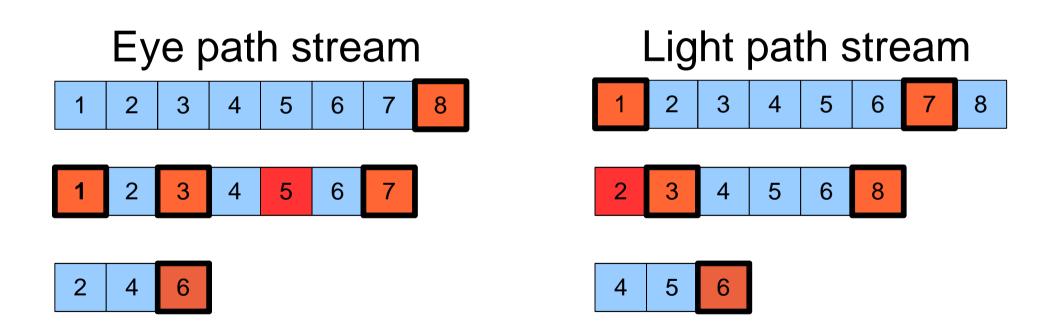


 Sample terminates when **both** eye and light path have terminated





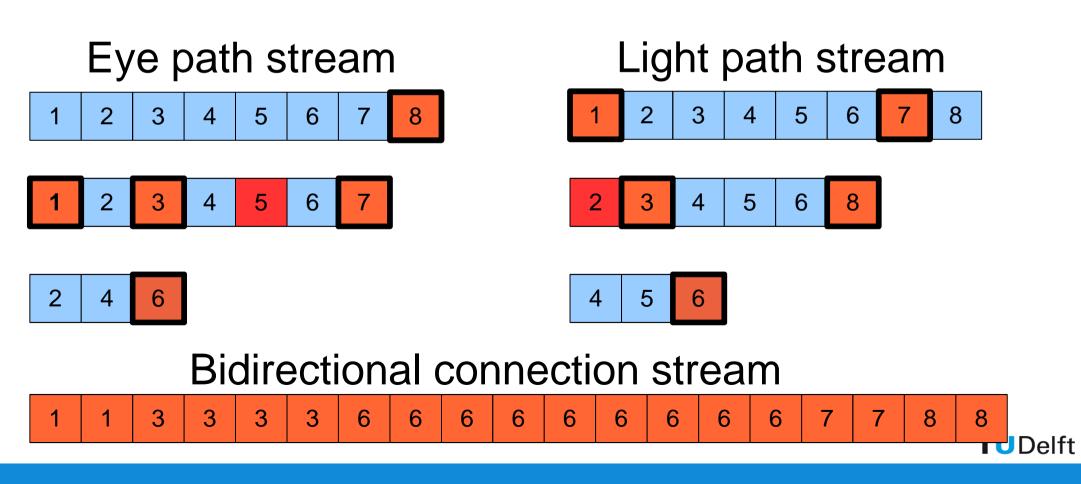
Repeat until 60% of samples terminated





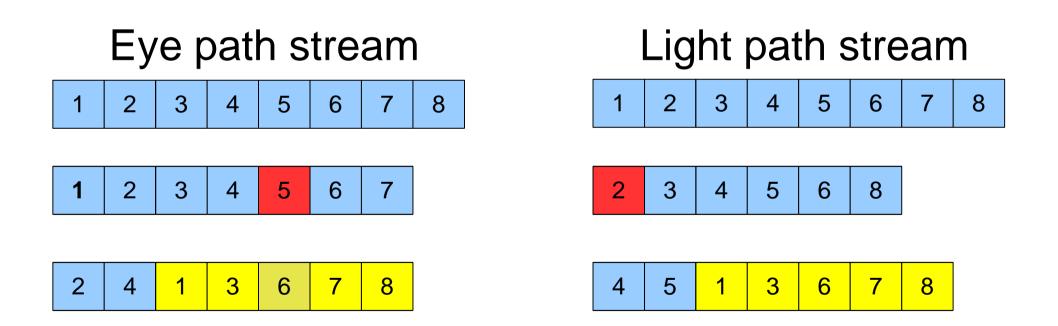
Bidirectional Connect Phase

- Evaluate connections for terminated samples
- Generate stream of bidirectional connections



Sample Regeneration

Regenerate terminated samples and resume random walk phase





Sample Regeneration

- Sample regeneration keeps path streams long
- Good for GPU utilization
- Total speedup ~15%
- Less than for path tracing
- Sample regeneration only improves random walk phase
- BDPT spends only ~55% in random walk phase



Bidirectional Connect Phase

- Evaluate all connection in parallel
- Each terminated sample contributes #connections
- Execute thread for each connection
- Threads figure out which connection to evaluate using
 - Parallel scan over all samples
 - Binary search for each connection thread
- See paper for details...



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Metropolis Light Transport

- Run many independent MLT samplers in parallel
- Based on the BDPT implementation
- Use variation on Kelemen mutation
- Only mutate sample dimensions used in both current and mutated sample
- Estimate normalization constant on the fly



Startup Bias

- Each MLT sampler introduces startup bias
- Many parallel samplers means lots of bias
- Bias is usually larger for difficult scenes









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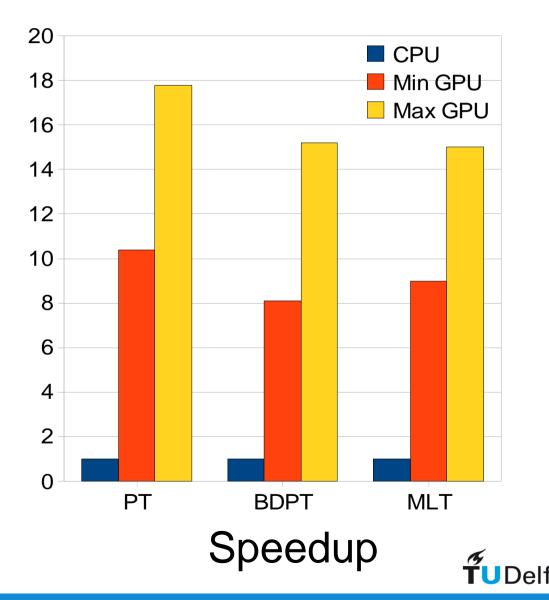
SIMD efficiency

- Algorithms always work on continuous streams
- Active threads per GPU warp ~99%
- Upper bound on actual SIMD efficiency
- Actual SIMD efficiency lower due to divergent shader/traversal code
- Performance improvement less than SIMD efficiency improvement...

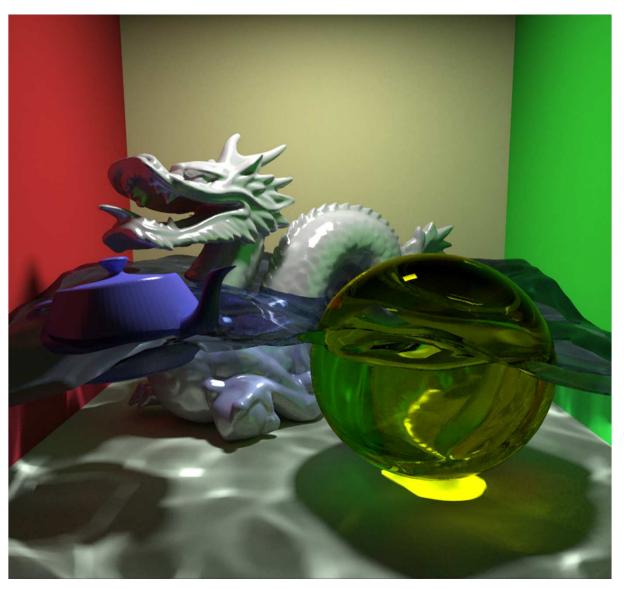


GPU vs. CPU

- Compared with straightforward multicore CPU implementation
- NVIDIA GTX 480 GPU
- Intel Core i7 920 CPU
- Speedup between 8x and 15x
- GPU can do more than path tracing!



Demo





Questions?



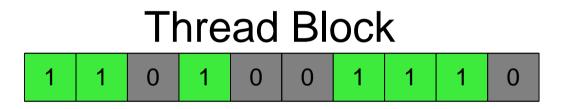
Extra



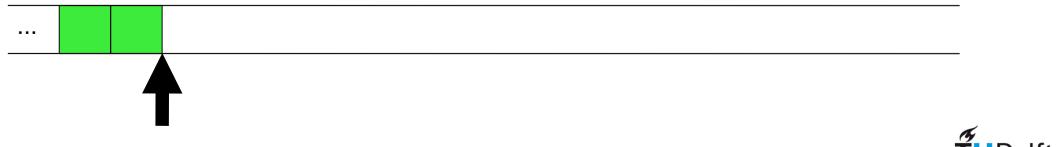
- Stream compaction requires multi-pass parallel scan and scatter pass
- Immediate stream compaction in single pass
- Parallel scan per block in shard memory
- Block allocates space in output buffer using one atomic add
- Threads write items directly into compacted output stream



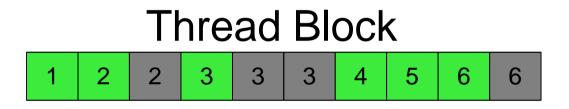
• Label all active threads



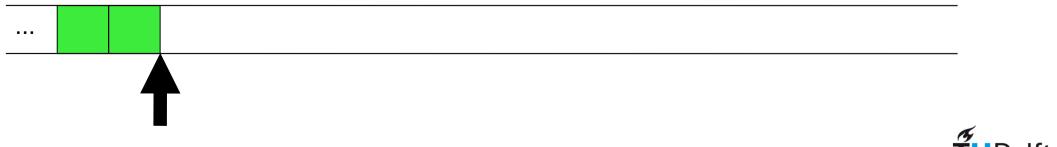




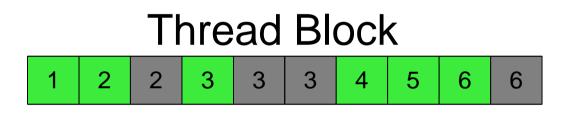
• Parallel scan per block in shared memory

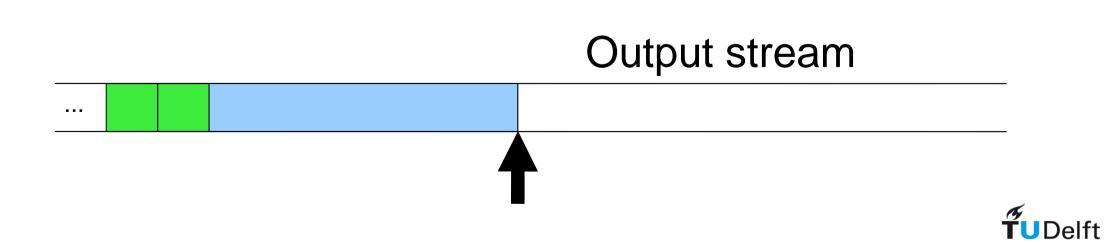




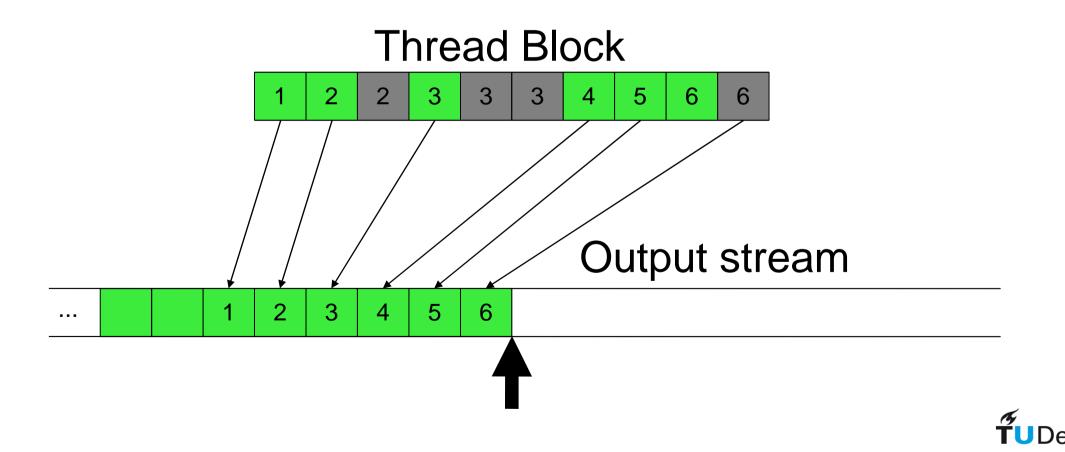


 Block allocates memory in output stream using an atomic instruction

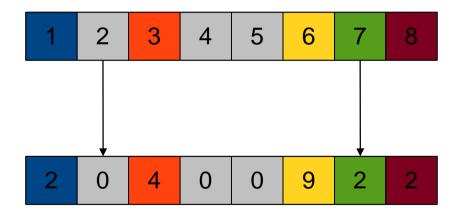




Each active thread writes directly in the output stream

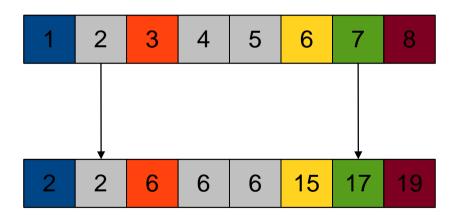


- Each sample writes #connections in connection count buffer
- Non-terminated samples write a zero



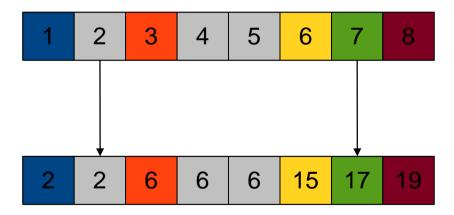


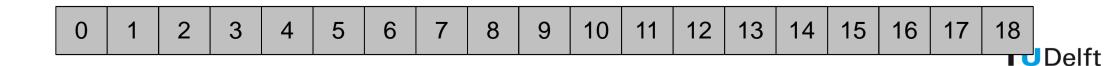
- Parallel scan the connection count buffer
- Gives the #connections preceding each sample in the buffer



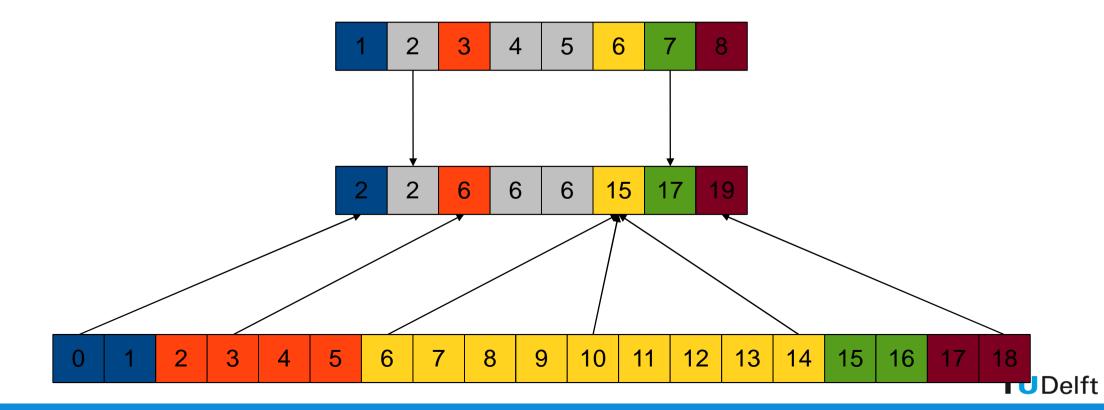


Start one GPU thread for each connection

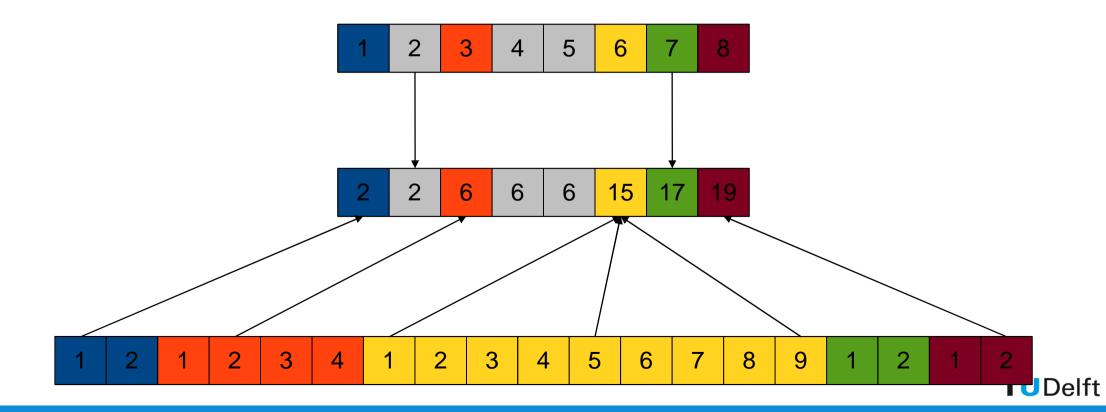




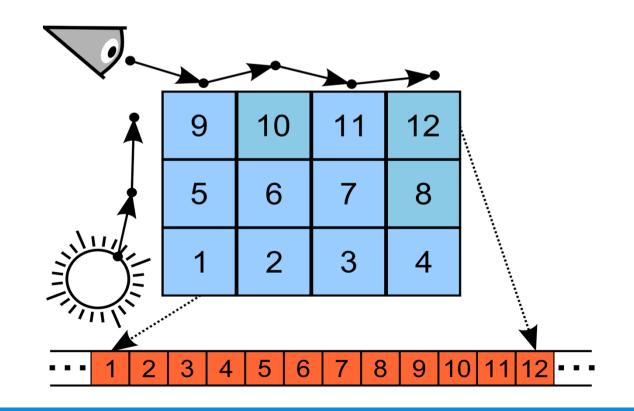
Binary search thread index for corresponding sample in connection count buffer



 Compute local connection index from sample connection count



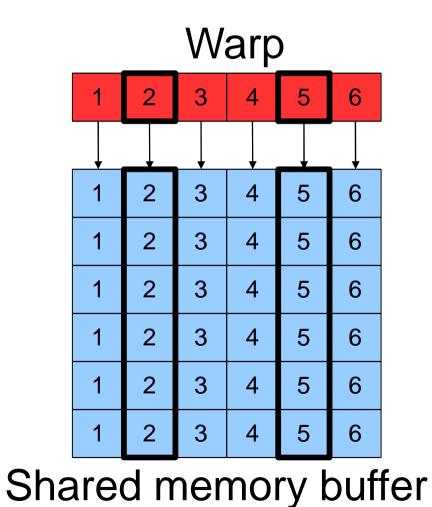
- Local connection indices map to an eye-light vertex pair to connection
- Each thread evaluates its connection





- Path vertices are stored during random walk
- Vertices are scattered to pre-allocated vertex memory
- Each thread scattering its vertex would result in uncoalesced memory access
- Threads in a warp collaborate to efficiently scatter path vertices to memory
- Vertices are scattered through shared memory
- Similar to matrix transpose

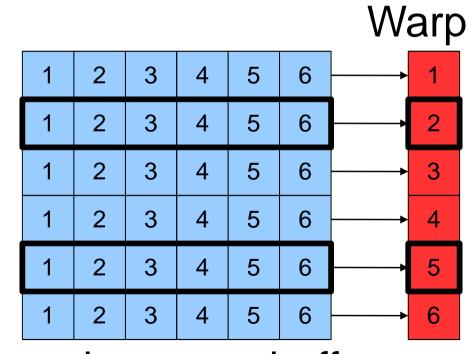




- Vertex is 128 bytes
- Each thread in warp writes vertex to shared memory



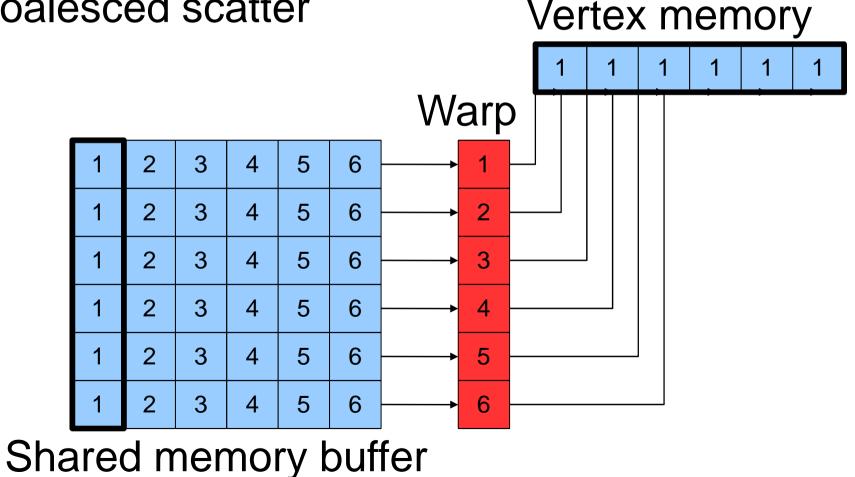
Each thread in warp reads one word from each vertex in shared memory buffer



Shared memory buffer

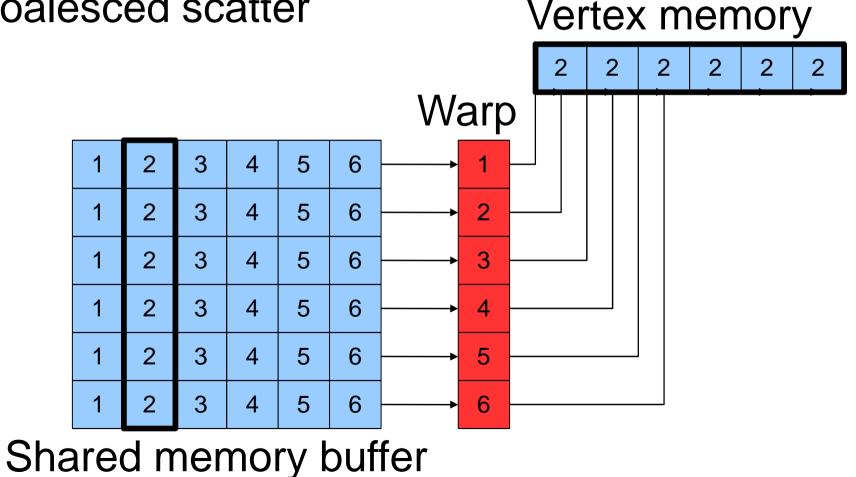


- Each thread scatters one word of each vertex
- Coalesced scatter



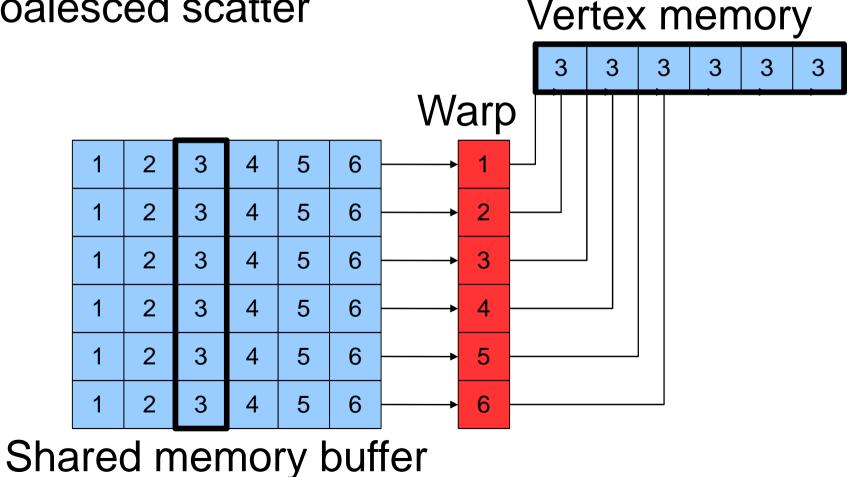


- Each thread scatters one word of each vertex
- Coalesced scatter





- Each thread scatters one word of each vertex
- Coalesced scatter





Mutation Strategy

- Kelemen et al. proposed to lazily perturb all infinite dimensions
- Leads to uneven workload during mutation
- Instead, perturb only dimensions used in both the current and mutated sample
- Regenerate other dimensions
- Keeps the strategy symmetric
- Reduces memory usage
- Even workload per path vertex

