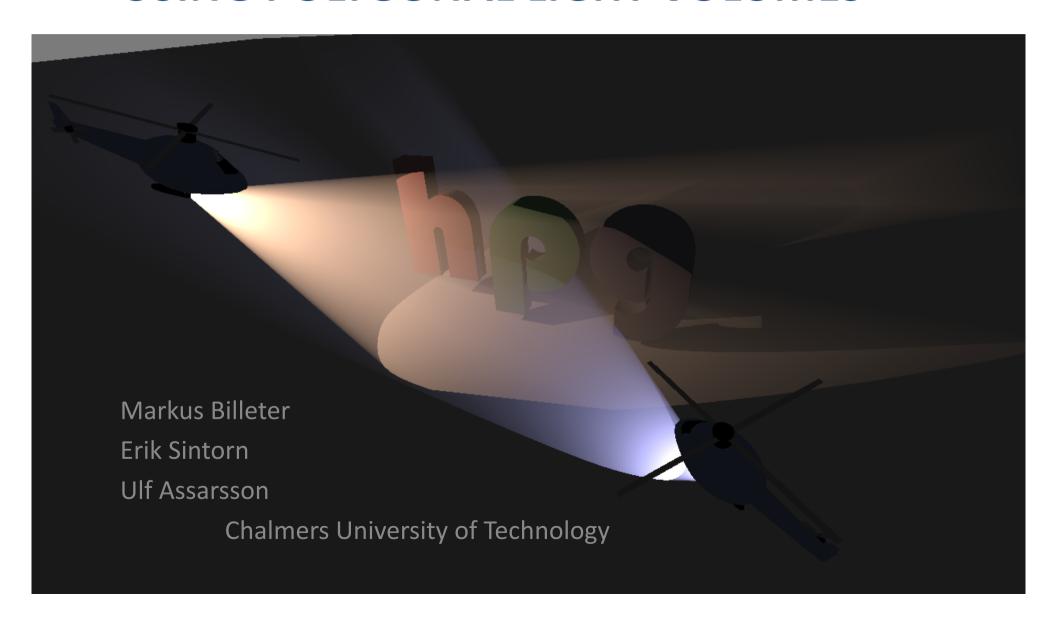
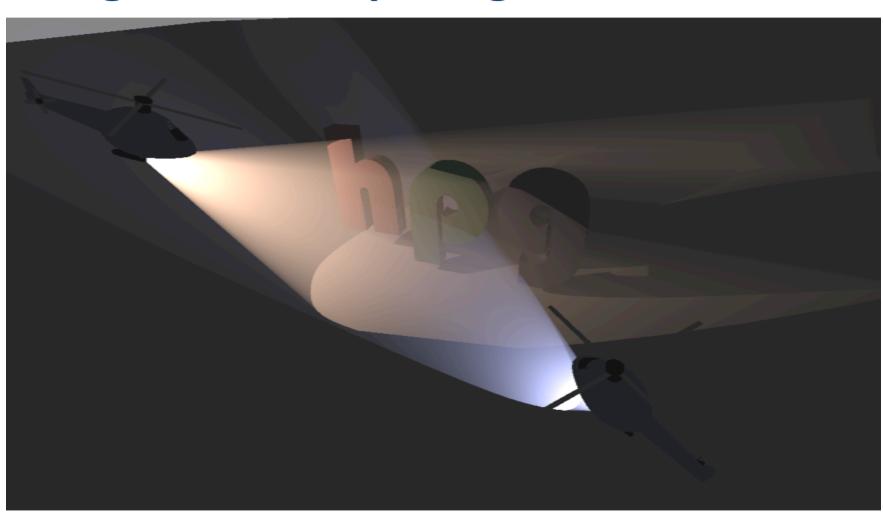
REAL TIME VOLUMETRIC SHADOWS USING POLYGONAL LIGHT VOLUMES



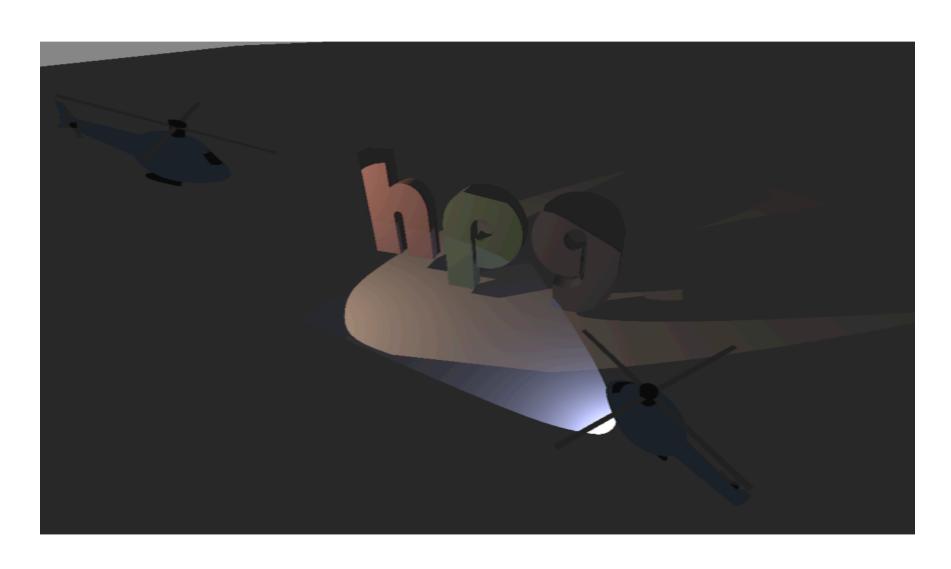
Overview

- Introduction: Airlight
- From Ray Marching to Light Volumes
- Light Volume Algorithm
- Adaptive Tessellation
- Demo / Movie
- Results
- Conclusion

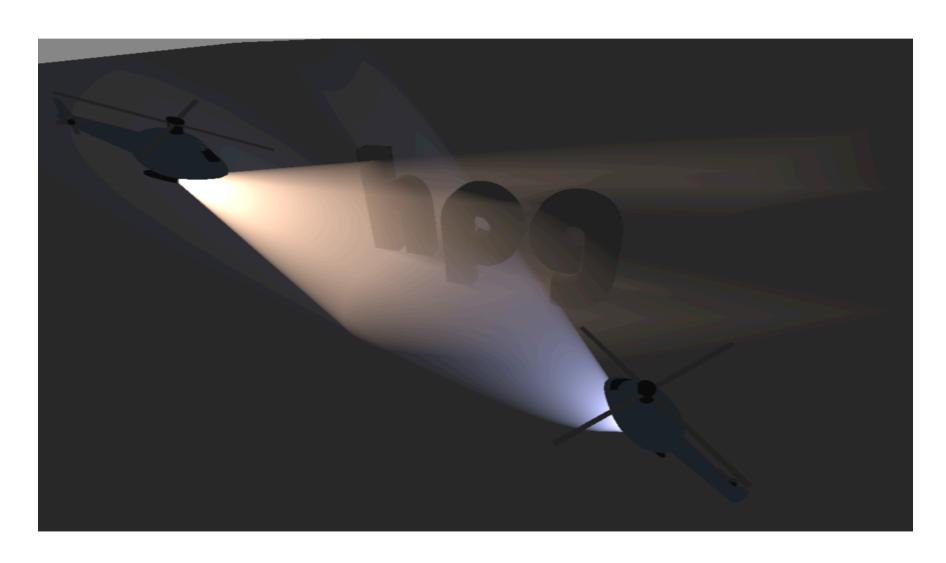
Introduction: Airlight / Participating Media



Direct Light and Hard Shadows Only

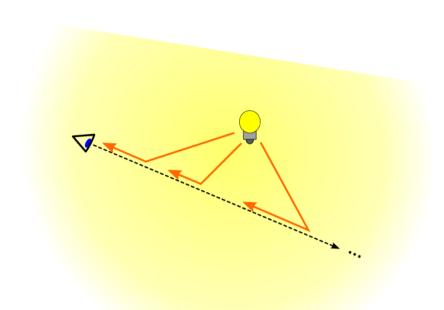


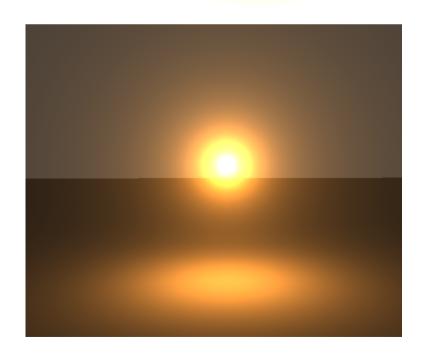
Airlight / Participating Media Only



Airlight

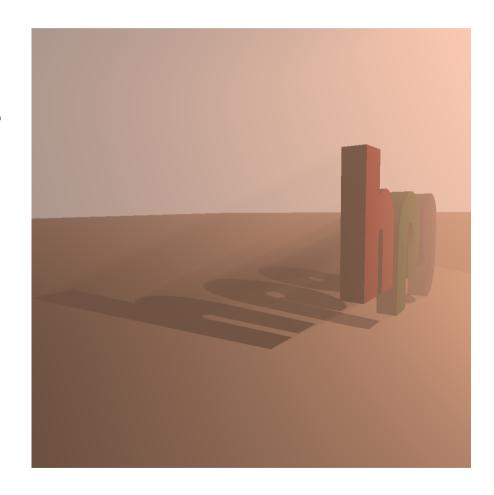
- Use single scattering model
 - Integral along ray
 - Nishita et al. in 1987
- Direct solution using texture lookups
 - Gives in-scattered light(Airlight) on line segment
 - E.g. Sun et al. in 2005
- Ignores occlusion





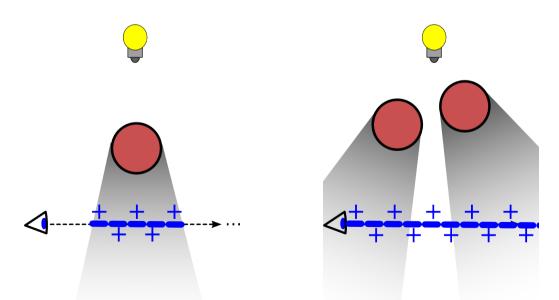
Ray-marching

- Ray march to find illuminated regions
 - At each point, determine if illuminated
- Done with
 - alpha blended planes
 - Dobashi et al. in 2002
 - Imagire et al. in 2007
 - Loop in fragment shader
 - E.g. Toth and Umenhoffer in 2009

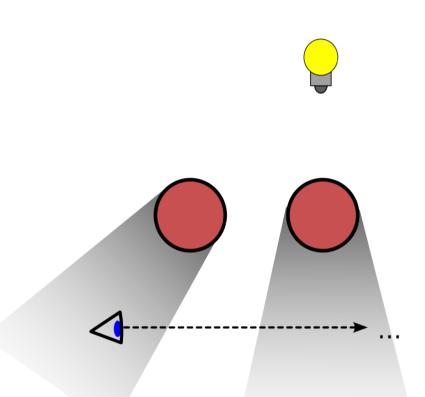


Ray-marching, Improved

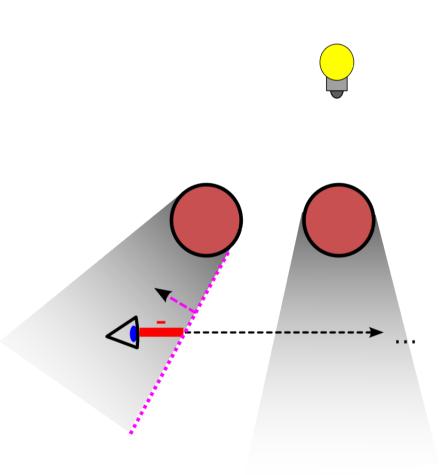
- Limit ray marched regions
 - Use shadow volumes to bound interesting region
 - Wyman et al. in 2008
- Cases where the bounds don't help...



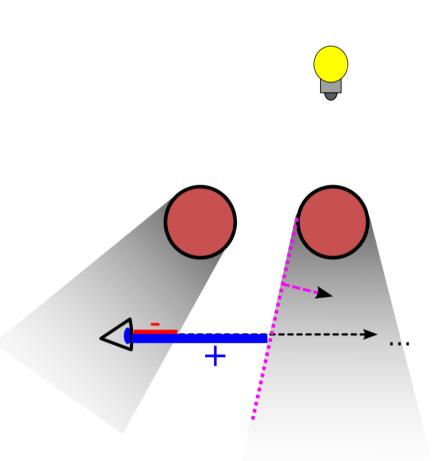
- Avoid ray marching entirely
 - Lit range on ray can be evaluated directly
 - Need to find ranges/ boundaries
- ⇒ Shadow Volumes!



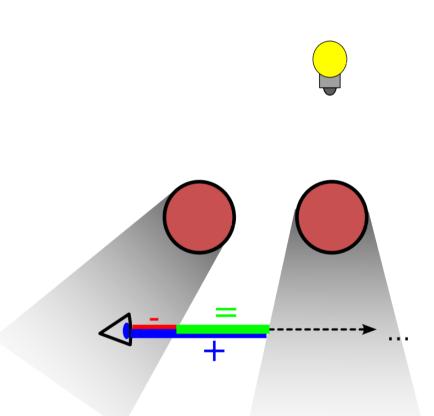
- Avoid ray marching entirely
 - Lit range on ray can be evaluated directly
 - Need to find ranges/ boundaries
- ⇒ Shadow Volumes!



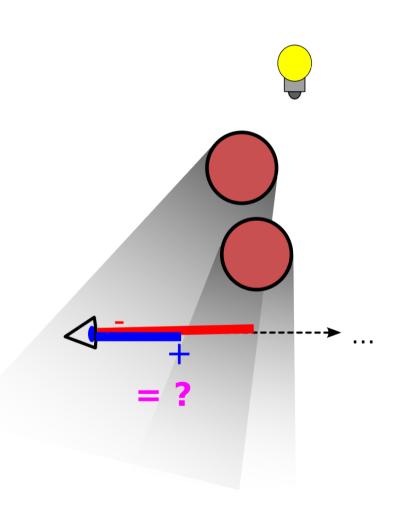
- Avoid ray marching entirely
 - Lit range on ray can be evaluated directly
 - Need to find ranges/ boundaries
- ⇒ Shadow Volumes!



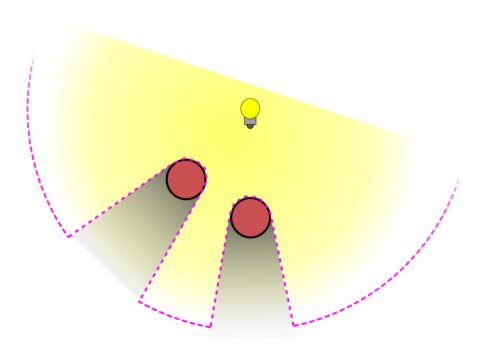
- Avoid ray marching entirely
 - Lit range on ray can be evaluated directly
 - Need to find ranges/ boundaries
- ⇒ Shadow Volumes!



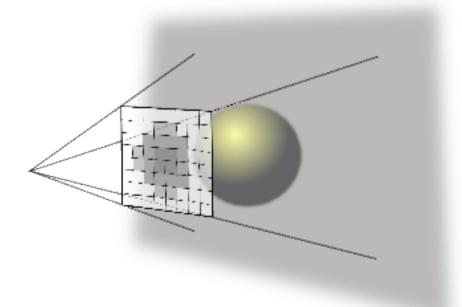
- Avoid ray marching entirely
 - Lit range on ray can be evaluated directly
 - Need to find ranges/ boundaries
- ⇒ Shadow Volumes!
- Problems:
 - Overlapping Volumes



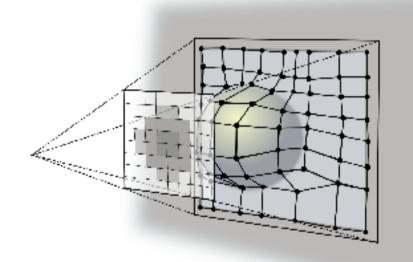
- Fix problems by:
 - Sort/depth peel volumes
 - Venceslas et. al. in 2006
 - James in 2003
- Reconstruct volume from shadow map!
 - Reconstruction explored by McCool in 2000
 - Use bounded light volume



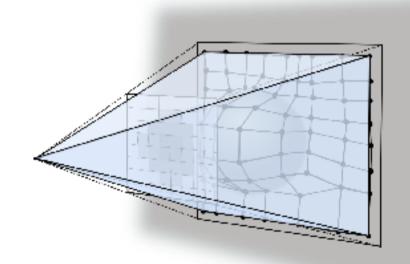
- Fix problems by:
 - Sort/depth peel volumes
 - Venceslas et. al. in 2006
 - James in 2003
- Reconstruct volume from shadow map!
 - Reconstruction explored by McCool in 2000
 - Use bounded light volume



- Fix problems by:
 - Sort/depth peel volumes
 - Venceslas et. al. in 2006
 - James in 2003
- Reconstruct volume from shadow map!
 - Reconstruction explored by McCool in 2000
 - Use bounded light volume

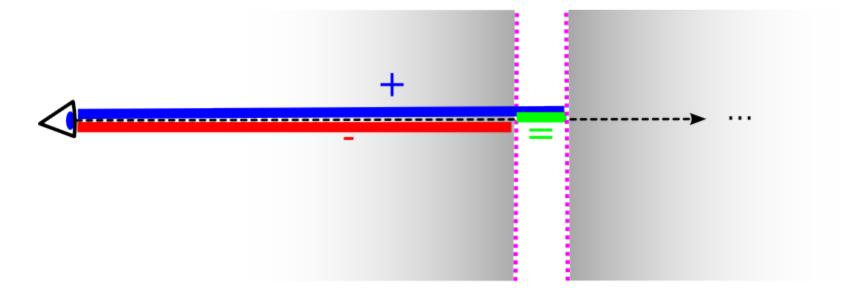


- Fix problems by:
 - Sort/depth peel volumes
 - Venceslas et. al. in 2006
 - James in 2003
- Reconstruct volume from shadow map!
 - Reconstruction explored by McCool in 2000
 - Use bounded light volume



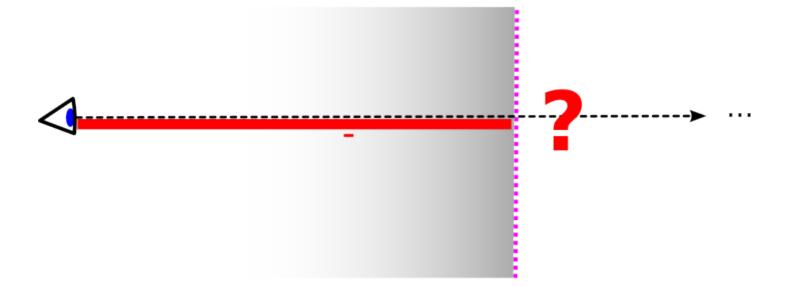
Problems

- Shadow maps are inherently inexact
 - Sampling errors, quantization errors
- Very important: must not miss transitions!
 - Add and subtract large values



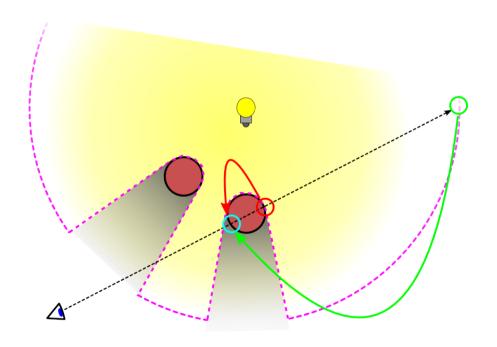
Problems

- Shadow maps are inherently inexact
 - Sampling errors, quantization errors
- Very important: must not miss transitions!
 - Add and subtract large values



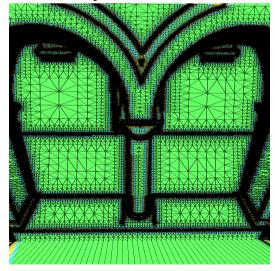
Solution: Clamp Transitions

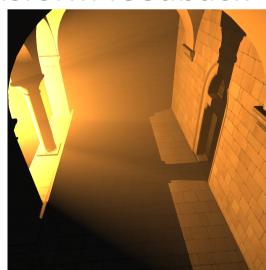
- Don't use Z-culling of volumes
 - clamp to screen-space Z
- Example Figure:
 - Two identical contributions after clamp...
 - ⇒ ...will cancel
- ⇒ Airlight behind visible objects will never contribute to the final image.



Adaptive Tessellation

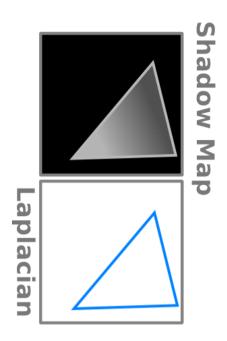
- Light volume: potentially lots of geometry
 - @ 1024^2 : ~2M triangles
 - Use adaptive tessellation to reduce this
- Tessellation performed with
 - Geometry shaders and transform feedback

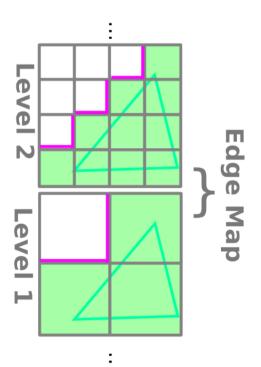




Adaptive Tessellation

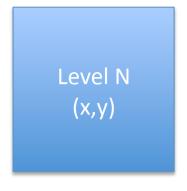
- Find edges in shadow map (Laplacian)
- Build edge map
 - Mip-map hierarchy
- Each texel contains:
 - Subdivision required?
 - Stitching (neighborhood) information
- Ensure max 1-level of difference between neighbors





Adaptive Tessellation

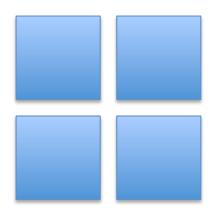
Input:



+ edge map at level N @ (x,y)

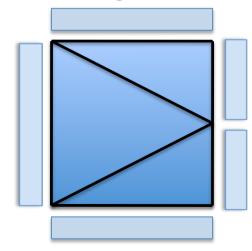
If(subdivide):

- Emit four smaller quads
- Repeat (Level N+1)



Else:

- Check neighbor-information
- Emit triangles



Adaptive Tessellation Performance

- Reduces triangles by
 - Sibenik: at least 50% for 1024^2 shadow maps
 - Average: 30% triangles compared to static tessellation
 - Sponza: at least 60% for 1024^2 shadow maps
 - Average: 30% triangles compared to static tessellation
- Not an exhaustive test

Cu cu zo 2	Lanlasian	0.66	
Sponza2 1024^2 SM	Laplacian	0.66ms	
	Edge Map	0.68ms	
	Tessellate	3.11ms	
	Render	7.51ms	
Statio	9.0ms		
Sponza2 4096^2 SM	Laplacian	10.11ms	
	Edge Map	9.14ms	
	Tessellate	4.13ms	
	Render	17.75ms	
Statio	93.9ms		

- NVIDIA GTX280
- Same as paper!

Demo / Movie

- Recorded on a NVIDIA GTX 480
 - Resolution is 1024x768 in all clips
 - Performance figures on next slide!

Scene: Sponza2

- 5 light sources
- 512^2 shadow map
- 100 FPS on average

Demo / Movie

- Recorded on a NVIDIA GTX 480
 - Resolution is 1024x768 in all clips
 - Performance figures on next slide!
- Live Demo session
 - On this notebook (9400M)

Results - Performance

	Shadow Maps	Adaptive Tessellation	Draw Volumes	Render Scene	TOTAL
Sponza2 5x 512^2	5.2ms	-	1.3ms	1.0ms	9.7ms
Sibenik 2x 1024^2	0.9ms	-	3.9ms	1.9ms	9.4ms
HPG 1x 1024^2	0.2ms	0.6ms	0.3ms	0.2ms	3.3ms

- NVIDIA GTX480
- View resolution: 1024x768
- Constant overhead: around 2ms
 - Information, post-processing, composition

Conclusions

- Only uses information from the shadow and depth map
 - Handles alpha masks, etc
 - Easy to add to existing programs (additional pass)
 - Shadow map size can be scaled
- However: does not handle textured lights
 - And only homogenous media
 - ⇒Better solutions to the Single Scattering Integral?

THANK YOU FOR YOUR ATTENTION!

